## THE BILBAO CRYSTALLOGRAPHIC SERVER:

## CRYSTALLOGRAPHIC DATABASES AND COMPUTER PROGRAMS

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## bilbao crystallographic server

[ The crystallographic site at the Condensed Matter Physics Dept. of the University of the Basque Country ]
[ Space Groups ] [ Layer Groups ] [ Rod Groups ] [ Frieze Groups ] [ Wyckoff Sets ]

First announcement and pre-registration of a School in 2009 on

| CrystallographyOnline: |
| :--- |
| InternationalSchoolon |
| theUseondApplications |
| of heBilbao |
| Crystallographic |
| Server |

## Sections

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Space Groups Retrieval Tools

| GENPOS | Generators and General Positions of Space Groups |
| :--- | :--- |
| WYCKPOS | Wyckoff Positions of Space Groups |
| HKLCOND | Reflection conditions of Space Groups |
| MAXSUB | Maximal Subgroups of Space Groups |
| SERIES | Series of Maximal Isomorphic Subgroups of Space Groups |
| WYCKSETS | Equivalent Sets of Wyckoff Positions |
| NORMALIZER | Normalizers of Space Groups |
| KVEC | The k-vector types and Brillouin zones of Space Groups |

## Group - Subgroup Relations of Space Groups

| SUBGROUPGRAPH | Lattice of Maximal Subgroups |
| :--- | :--- |
| HERMANN | Distribution of subgroups in conjugated classes |
| COSETS | Coset decomposition for a group-subgroup pair |
| WYCKSPLIT | The splitting of the Wyckoff Positions |
| MINSUP | Minimal Supergroups of Space Groups |
| SUPERGROUPS | Supergroups of Space Groups |
| CELLSUB | List of subgroups for a given k-index. |
| CELLSUPER | List of supergroups for a given k-index. |
| COMMONSUBS | Common Subgroups of Space Groups |
| COMMONSUPFR | Common Sunerarouns of Two Snace Grouns |

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## Crystallographic databases

## Group-subgroup relations

## Structural utilities

## Representations of point and space groups

Solid-state applications

# Crystallographic Databases 

## International Tables for Crystallography





## Space-group Data

International Tables for Crystallography

Volume A: Space-group symmetry
generators
Wyckoff positions
Wyckoff sets
normalizers

Volume AI: Symmetry Relations between space groups
maximal subgroups of index 2,3 and 4
series of isomorphic subgroups

Retrieval tools


```
Maximal non-isomorphic subgroups
I \begin{tabular}{ll}
{\([2] P 411(P 4,75)\)} & \(1 ; 2 ; 3 ; 4\) \\
{\([2] P 21 m(C m m 2,35)\)} & \(1 ; 2 ; 7 ; 8\) \\
{\([2] P 2 m 1(P m m 2,25)\)} & \(1 ; 2 ; 5 ; 6\)
\end{tabular}
```

IIa none
IIb $\quad[2] P 4_{2} m c\left(\mathbf{c}^{\prime}=2 \mathbf{c}\right)(105) ;[2] P 4 c c\left(\mathbf{c}^{\prime}=2 \mathbf{c}\right)(103) ;[2] P 4_{2} c m\left(\mathbf{c}^{\prime}=2 \mathbf{c}\right)(101) ;[2] C 4 m d\left(\mathbf{a}^{\prime}=2 \mathbf{a}, \mathbf{b}^{\prime}=2 \mathbf{b}\right)(P 4 b m, 100)$;
$[2] F 4^{2} m c\left(\mathbf{a}^{\prime}=2 \mathbf{a}, \mathbf{b}^{\prime}=2 \mathbf{b}, \mathbf{c}^{\prime}=2 \mathbf{c}\right)(I 4 \mathrm{~cm}, 108) ;[2] F 4 m m\left(\mathbf{a}^{\prime}=2 \mathbf{a}, \mathbf{b}^{\prime}=2 \mathbf{b}, \mathbf{c}^{\prime}=2 \mathbf{c}\right)(I 4 \mathrm{~mm}, 107)$

## Maximal isomorphic subgroups of lowest index

IIc $\quad[2] P 4 m m\left(\mathbf{c}^{\prime}=2 \mathbf{c}\right)(99) ;[2] C 4 m m\left(\mathbf{a}^{\prime}=2 \mathbf{a}, \mathbf{b}^{\prime}=2 \mathbf{b}\right)(P 4 m m, 99)$

```
Minimal non-isomorphic supergroups
I [2]P4/mmm(123); [2]P4/nmm(129)
II [2]I4mm(107)
```


## Generators and General Positions

## How to select the group

The space groups are specified by their number as given in the Intemational Tables for Crystallography, Vol. A. You can give this number, if you know it, or you can choose it from the table with the space group numbers and symbols if you click on the button [choose it].

Please, enter the sequential number of group as given in the Intemational Tables for Crystallography, Vol. A or

| Show: | Generators only <br> All General Positions |
| :--- | :--- |



ITA-settings symmetry data

## PRACTICAL EXERCISES

Bilbao Crystallographic Server www.cryst.ehu.es

Bilbao Crystallographic Server - mirror site http://158.227.0.68/

# MATRIX-COLUMN PRESENTATION OF SYMMETRY OPERATIONS 

## Crystallographic symmetry operations

## Symmetry operations of an object

The isometries which map the object onto itself are called symmetry operations of this object. The symmetry of the object is the set of all its symmetry operations.

## Crystallographic symmetry operations

If the object is a crystal pattern, representing a real crystal, its symmetry operations are called crystallographic symmetry operations.


The equilateral triangle allows six symmetry operations: rotations by 120 and 240 around its centre, reflections through the three thick lines intersecting the centre, and the identity operation.

## Description of isometries

## coordinate system:

$\{O, \mathbf{a}, \mathbf{b}, \mathbf{c}\}$
isometry:
point $X \longrightarrow$ point $\tilde{X}$

$$
\begin{aligned}
& \tilde{x}=W_{11} x+W_{12} y+W_{13} z+w_{1} \\
& \tilde{y}=W_{21} x+W_{22} y+W_{23} z+w_{2} \\
& \tilde{z}=W_{31} x+W_{32} y+W_{33} z+w_{3}
\end{aligned}
$$

## Matrix formalism

$$
\begin{aligned}
& \left(\begin{array}{l}
\tilde{x} \\
\tilde{y} \\
\tilde{z}
\end{array}\right)=\left(\begin{array}{l}
W_{11} W_{12} W_{13} \\
W_{21} W_{22} W_{23} \\
W_{31} W_{32} W_{33}
\end{array}\right)\left(\begin{array}{l}
x \\
y \\
z
\end{array}\right)+\left(\begin{array}{l}
w_{1} \\
w_{2} \\
w_{3}
\end{array}\right) \\
& \text { linear/matrix } \\
& \text { part }
\end{aligned}
$$

$$
\begin{aligned}
& \tilde{\boldsymbol{x}}=\boldsymbol{W} \boldsymbol{x}+\boldsymbol{w} \\
& \tilde{\boldsymbol{x}}=(\boldsymbol{W}, \boldsymbol{w}) \boldsymbol{x} \text { or } \tilde{\boldsymbol{x}}=\{\boldsymbol{W} \mid \boldsymbol{w}\} \boldsymbol{x}
\end{aligned}
$$

matrix-column pair

## Matrix formalism

## combination of isometries:

$\left(\boldsymbol{W}_{2}, \boldsymbol{w}_{2}\right)\left(\boldsymbol{W}_{1}, \boldsymbol{w}_{1}\right)=\left(\boldsymbol{W}_{2} \boldsymbol{W}_{1}, \boldsymbol{W}_{2} \boldsymbol{w}_{1}+\boldsymbol{w}_{2}\right)$
inverse isometries:

$$
(\boldsymbol{W}, \boldsymbol{w})^{-1}=\left(\boldsymbol{W}^{-1},-\boldsymbol{W}^{-1} \boldsymbol{w}\right)
$$

## Matrix formalism: $4 \times 4$ matrices

augmented matrices:

$$
\left.\begin{array}{l}
\boldsymbol{x} \rightarrow \star=\left(\begin{array}{c}
x \\
y \\
z \\
\hline 1
\end{array}\right) ; \tilde{\boldsymbol{x}} \rightarrow \tilde{\mathfrak{z}}=\left(\begin{array}{c}
\tilde{x} \\
\tilde{y} \\
\tilde{z} \\
\hline 1
\end{array}\right) \\
(\boldsymbol{W}, \boldsymbol{w}) \rightarrow \mathbb{W}=\left(\begin{array}{ll|l}
\boldsymbol{W} & \boldsymbol{W} & \boldsymbol{w} \\
& & \\
\hline 0 & 0 & 0
\end{array}\right. \\
\hline \boldsymbol{\tilde { V }}
\end{array}\right)
$$

## point $X \longrightarrow$ point $\tilde{X}$ :

$$
\tilde{\otimes}=\mathbb{W} \mathbb{x}
$$

$$
\left(\begin{array}{c}
\tilde{x} \\
\tilde{y} \\
\tilde{z} \\
\hline 1
\end{array}\right)=\left(\begin{array}{ccc|c} 
& \boldsymbol{W} & & \boldsymbol{w} \\
& & & \\
\hline 0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{c}
x \\
y \\
z \\
\hline 1
\end{array}\right)
$$

## $4 \times 4$ matrices: general formulae

point $X \longrightarrow$ point $\tilde{X}:$

$$
\tilde{\mathbb{x}}=\mathbb{W} \mathbb{\mathbb { x }} \quad\left(\begin{array}{c}
\tilde{x} \\
\tilde{y} \\
\tilde{z} \\
\hline 1
\end{array}\right)=\left(\begin{array}{lll|l} 
& & & \\
& \boldsymbol{W} & & \boldsymbol{w} \\
& & & \\
\hline 0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{c}
x \\
y \\
z \\
\hline 1
\end{array}\right)
$$

combination and inverse of isometries:
$(\mathbb{W})^{-1}=\left(\mathbb{W}^{-1}\right) \quad \mathbb{W}^{-1}=\left(\begin{array}{ccc|c} & W^{-1} & -W^{-1} \boldsymbol{w} \\ & & & 1\end{array}\right)$
$\mathbb{W}_{3}=\mathbb{W}_{2} \mathbb{W}_{1}$

## EXERCISES

## Problem I.I

Construct the matrix column pair (W,w) (and the corresponding ( $4 \times 4$ ) matrix) of the following coordinate triplets:
(I) $x, y, z$
(2) $-x, y+1 / 2,-z+1 / 2$
(3) $-x,--y,-z$
(4) $x,-y+I / 2, z+I / 2$

## GEOMETRIC MEANING OF MATRIX-COLUMN PAIRS (W,w)

## Crystallographic symmetry operations

characteristics:

## fixed point $\tilde{P}=P$ <br> of isometries

## Types of isometries preserve handedness

identity:
translation t :
rotation:
screw rotation:
the whole space fixed
no fixed point $\quad \tilde{\mathbf{x}}=\mathbf{x}+\mathbf{t}$
one line fixed rotation axis

$$
\phi=k \times 360^{\circ} / N
$$

no fixed point screw axis

## Types of isometries

## do not

 preserve handedness
## roto-inversion:

inversion:

## reflection:

## glide reflection:

plane fixed reflection/mirror plane

## centre of roto-inversion fixed roto-inversion axis

## centre of inversion fixed

no fixed point glide plane
glide vector

## Geometric meaning of $(W, w)$

## $W$ information

## (a) type of isometry

| $\operatorname{tr}(\boldsymbol{W})$ | $\operatorname{det}(\boldsymbol{W})=+1$ |  |  |  | $\operatorname{det}(\boldsymbol{W})=-1$ |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 3 | 2 | 1 | 0 | -1 | -3 | -2 | -1 | 0 | 1 |
|  | 1 | 6 | 4 | 3 | 2 | $\overline{1}$ | $\overline{6}$ | $\overline{4}$ | $\overline{3}$ | $\overline{2}=m$ |
| order | 1 | 6 | 4 | 3 | 2 | 2 | 6 | 4 | 6 | 2 |

rotation angle

$$
\cos \varphi=( \pm \operatorname{tr}(\boldsymbol{W})-1) / 2
$$

## Geometric meaning of $(W, w)$

## $W$ information

(b) axis or normal direction $\boldsymbol{u}$ :

$$
\boldsymbol{W} \boldsymbol{u}= \pm \boldsymbol{u}
$$

## (bl) rotations:

$\boldsymbol{Y}(\boldsymbol{W})=\boldsymbol{W}^{k-1}+\boldsymbol{W}^{k-2}+\ldots+\boldsymbol{W}+\boldsymbol{I}$
(b2) roto-inversions: $\quad \boldsymbol{Y}(-\boldsymbol{W})$
reflections: $\quad \boldsymbol{Y}(-\boldsymbol{W})=-\boldsymbol{W}+\boldsymbol{I}$

## Geometric meaning of $(W, w)$

## $W$ information

(c) sense of rotation:

## for rotations or rotoinversions with $k>2$

$$
\operatorname{det}(\boldsymbol{Z}): \boldsymbol{Z}=[\boldsymbol{u}|\boldsymbol{x}|(\operatorname{det} \boldsymbol{W}) \boldsymbol{W} \boldsymbol{x}]
$$

$\boldsymbol{x}$ non-parallel to $\boldsymbol{u}$

## Geometric meaning of $(W, w)$

## $w$-information

## (A) intrinsic translation part :

## glide or screw component

(AI) screw rotations:

$$
\boldsymbol{t} / k=\frac{1}{k} \boldsymbol{Y} \boldsymbol{w}, \text { where } \boldsymbol{W}^{k}=\boldsymbol{I}
$$

(A2) glide reflections:

$$
\boldsymbol{t} / k=\frac{1}{2}(\boldsymbol{W}+\boldsymbol{I})
$$

## Geometric meaning of $(W, w)$

## $w$-information

## (B) location (fixed points $x_{F}$ ):

$$
\begin{array}{rr}
\text { (BI) } \boldsymbol{t} / k=\mathbf{0}: & (\boldsymbol{W}, \boldsymbol{w}) \boldsymbol{x}_{F}=\boldsymbol{x}_{F} \\
& \\
\text { (B2) } \boldsymbol{t} / k \neq \mathbf{0}: & \left(\boldsymbol{W}, \boldsymbol{w}_{l p}\right) \boldsymbol{x}_{F}=\boldsymbol{x}_{F} \\
& \boldsymbol{w}_{l p}=\boldsymbol{w}-\boldsymbol{t} / k
\end{array}
$$

## EXERCISES

## Problem I.I (cont.)

Construct the matrix-column pairs (W,w) (and the corresponding $(4 \times 4)$ matrices) of the following coordinate triplets:
(I) $x, y, z$
(2) $-x, y+1 / 2,-z+1 / 2$
(3) $-x,-y,-z$
(4) $x,-y+I / 2, z+I / 2$

Characterize geometrically these matrix-column pairs taking into account that they refer to a monoclinic basis with unique axis b, i.e. determine (i) the type, (ii) glide (screw) components, (iii) fixed points, (iv) nature and location of the symmetry elements.

## Problem I.I

## SOLUTION

(i)

$$
\begin{aligned}
& W(1)=\left(\begin{array}{cc|c}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 0 \\
\hline & 0 & 1
\end{array} 0\right. \\
& W(3)=\left(\begin{array}{cc|c}
\overline{1} & 0 & 0 \\
0 & \overline{1} & 0 \\
0 & 0 & \overline{1} \\
0 & 0 \\
\hline 0 & 0 & 0
\end{array}\right), W(4)=\left(\begin{array}{cc|c}
1 & 0 & 0
\end{array}\right) \begin{array}{c}
0 \\
0 \\
\hline
\end{array} 0
\end{aligned}
$$

(ii) ITA description: under Symmetry operations

| $(1)$ | $(2)$ | $(3)$ | $(4)$ |
| :---: | :---: | :---: | :---: |
| 1 | $2\left(0, \frac{1}{2}, 0\right) 0, y, \frac{1}{4}$ | $\overline{1} 0,0,0$ | $c x, \frac{1}{4}, z$ |

International Tables for Crystallography (2006). Vol. A, Space group 14, pp. 184-191.
$P 2_{1} / c$
No. 14
$C_{2 h}^{5}$
$P 12_{1} / c 1$
$2 / m$

UNIQUE AXIS $b$, CELL CHOICE 1


Generators selected (1); $t(1,0,0) ; t(0,1,0) ; t(0,0,1) ;(2) ;(3)$

## Positions

Multiplicity,
Coordinates
Wyckoff letter,
Site symmetry
$4 \quad e \quad 1$
(1) $x, y, z$
(2) $\bar{x}, y+\frac{1}{2}, \bar{z}+\frac{1}{2}$
(3) $\bar{x}, \bar{y}, \bar{z}$
(4) $x, \bar{y}+\frac{1}{2}, z+\frac{1}{2}$

Symmetry operations
(1) 1
(2) $2\left(0, \frac{1}{2}, 0\right) \quad 0, y, \frac{1}{4}$
(3) $\overline{1} \quad 0,0,0$
(4) $c \quad x, \frac{1}{4}, z$

## EXERCISES

## Problem 1.2

## Consider the matrices

$(\boldsymbol{A}, \boldsymbol{a})=\left(\begin{array}{ll}0 & 1\end{array} 0\right.$
(i) What is the matrix-column pair resulting from
$(\boldsymbol{B}, \boldsymbol{b})(\boldsymbol{A}, \boldsymbol{a})=(\boldsymbol{C}, \boldsymbol{c})$, and $(\boldsymbol{A}, \boldsymbol{a})(\boldsymbol{B}, \boldsymbol{b})=(\boldsymbol{D}, \boldsymbol{d})$ ?
(ii) What is $(\boldsymbol{A}, \boldsymbol{a})^{-1},(\boldsymbol{B}, \boldsymbol{b})^{-1},(\boldsymbol{C}, \boldsymbol{c})^{-1}$ and $(\boldsymbol{D}, \boldsymbol{d})^{-1}$ ?
(iii) What is $(\boldsymbol{B}, \boldsymbol{b})^{-1}(\boldsymbol{A}, \boldsymbol{a})^{-1}$ ?
(iv) The geometrical meaning of $(\boldsymbol{A}, \boldsymbol{a}),(\boldsymbol{B}, \boldsymbol{b}),(\boldsymbol{C}, \boldsymbol{c})$ and $(\boldsymbol{D}, \boldsymbol{d})$

## Problem I. 2

## SOLUTION

(i) $(\boldsymbol{B}, \boldsymbol{b})(\boldsymbol{A}, \boldsymbol{a}): \boldsymbol{B} \boldsymbol{A}=\left(\begin{array}{ccc}1 & 0 & 0 \\ 0 & 0 & \overline{1} \\ 0 & 1 & 0\end{array}\right), \boldsymbol{B} \boldsymbol{a}=\left(\begin{array}{c}1 / 2 \\ 1 / 2 \\ 1 / 2\end{array}\right)$,
$B a+b=B a$ for $b=o$.
Therefore, $(\boldsymbol{B} \boldsymbol{A}, \boldsymbol{B} a+\boldsymbol{b})=(\boldsymbol{C}, \boldsymbol{c})=\left(\begin{array}{ccc}1 & 0 & 0 \\ 0 & 0 & \overline{1} \\ 0 & 1 & 0\end{array}\right),\left(\begin{array}{c}1 / 2 \\ 1 / 2 \\ 1 / 2\end{array}\right)$.
Analogously one calculates
$(\boldsymbol{A}, \boldsymbol{a})(\boldsymbol{B}, \boldsymbol{b})=(\boldsymbol{D}, \boldsymbol{d})=\left(\begin{array}{ccc}0 & 0 & 1 \\ 0 & 1 & 0 \\ \overline{1} & 0 & 0\end{array}\right),\left(\begin{array}{c}1 / 2 \\ 1 / 2 \\ 1 / 2\end{array}\right)$.

## Problem I. 2

## SOLUTION

$$
\text { (ii) } \begin{aligned}
(\boldsymbol{A}, \boldsymbol{a})^{-1} & =\left(\begin{array}{lll}
0 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & \overline{1}
\end{array}\right),\left(\begin{array}{r}
-1 / 2 \\
-1 / 2 \\
1 / 2
\end{array}\right) ;(\boldsymbol{B}, \boldsymbol{b})^{-1}=\left(\begin{array}{lll}
0 & 0 & 1 \\
1 & 0 & 0 \\
0 & 1 & 0
\end{array}\right),\left(\begin{array}{l}
0 \\
0 \\
0
\end{array}\right) . \\
(\boldsymbol{C}, \boldsymbol{c})^{-1} & =\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 0 & 1 \\
0 & \overline{1} & 0
\end{array}\right),\left(\begin{array}{r}
-1 / 2 \\
-1 / 2 \\
1 / 2
\end{array}\right) ;(\boldsymbol{D}, \boldsymbol{d})^{-1}=\left(\begin{array}{lll}
0 & 0 & \overline{1} \\
0 & 1 & 0 \\
1 & 0 & 0
\end{array}\right),\left(\begin{array}{r}
1 / 2 \\
-1 / 2 \\
-1 / 2
\end{array}\right) .
\end{aligned}
$$

$$
\text { (iii) }(\boldsymbol{B}, \boldsymbol{b})^{-1}(\boldsymbol{A}, \boldsymbol{a})^{-1}=\left(\begin{array}{lll}
0 & 0 & \overline{1} \\
0 & 1 & 0 \\
1 & 0 & 0
\end{array}\right),\left(\begin{array}{r}
1 / 2 \\
-1 / 2 \\
-1 / 2
\end{array}\right)=(\boldsymbol{D}, \boldsymbol{d})^{-1} \neq(\boldsymbol{C}, \boldsymbol{c})^{-1} .
$$

Note, that $(\boldsymbol{B}, \boldsymbol{b})^{-1}(\boldsymbol{A}, \boldsymbol{a})^{-1}=[(\boldsymbol{A}, \boldsymbol{a})(\boldsymbol{B}, \boldsymbol{b})]^{-1}=(\boldsymbol{D}, \boldsymbol{d})^{-1}$.

## Problem I. 2

## SOLUTION

From the matrix parts the 'types' of the operations are determined by the determinants and traces:

|  | $\boldsymbol{A}$ | $\boldsymbol{B}$ | $\boldsymbol{C}$ | $\boldsymbol{D}$ |
| :---: | :---: | :---: | :---: | :---: |
| $\operatorname{det}$ | +1 | +1 | +1 | +1 |
| $\operatorname{tr}$ | $\overline{1}$ | 0 | 1 | 1 |
| type | 2 | 3 | 4 | 4 |

All the matrices are those of rotations. The directions [ $u v w$ ] of the rotation axes are determined by applying either equation 1.4 .11 or calculating the corresponding matri-

| $\boldsymbol{A}$ | $\boldsymbol{B}$ | $\boldsymbol{C}$ | $\boldsymbol{D}$ |
| :---: | :---: | :---: | :---: |
| $u=v$ | $u=v$ | $u=u$ | $u=w$ |
| $v=u$ | $v=w$ | $v=-w$ | $v=v$ |
| $w=-w$ | $w=u$ | $w=v$ | $w=-u$ |
| $[110]$ | $[111]$ | $[100]$ | $[010]$ | ces $\boldsymbol{Y}(\boldsymbol{W})$ :

## Problem I. 2

## SOLUTION

The matrix-column pair $(\boldsymbol{A}, \boldsymbol{a})$ : translation part

$$
\frac{1}{2}\left[\left(\begin{array}{lll}
0 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & 1
\end{array}\right)+\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right)\right]\left(\begin{array}{l}
1 / 2 \\
1 / 2 \\
1 / 2
\end{array}\right)=\frac{1}{2}\left(\begin{array}{lll}
1 & 1 & 0 \\
1 & 1 & 0 \\
0 & 0 & 0
\end{array}\right)\left(\begin{array}{c}
1 / 2 \\
1 / 2 \\
1 / 2
\end{array}\right)=\left(\begin{array}{c}
1 / 2 \\
1 / 2 \\
0
\end{array}\right)
$$

is the screw part of $(\boldsymbol{A}, \boldsymbol{a})$.
The reduced operation is $\left(\boldsymbol{A}, \boldsymbol{a}_{l p}\right)=\left(\begin{array}{lll}0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & \overline{1}\end{array}\right),\left(\begin{array}{c}0 \\ 0 \\ 1 / 2\end{array}\right)$.
$(A, a)$ : screw rotation 2 । screw rotation axis $\mathrm{x}, \mathrm{x}, \mathrm{I} / 4$
$(\boldsymbol{B}, \boldsymbol{b})$ : rotation 3
rotation axis $\mathrm{x}, \mathrm{x}, \mathrm{x}$
$3^{-} x, x, x$

## Problem I. 2

## SOLUTION

The matrix-column pair $(\boldsymbol{C}, \boldsymbol{c})$ : translation part

$$
\begin{aligned}
& \frac{\boldsymbol{t}}{4}=\frac{1}{4}\left[\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 0 & 1 \\
0 & \overline{1} & 0
\end{array}\right)+\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & \overline{1} & 0 \\
0 & 0 & \overline{1}
\end{array}\right)+\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 0 & \overline{1} \\
0 & 1 & 0
\end{array}\right)+\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right)\right]\left(\begin{array}{l}
1 / 2 \\
1 / 2 \\
1 / 2
\end{array}\right)= \\
& =\frac{1}{4}\left(\begin{array}{lll}
4 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{array}\right)\left(\begin{array}{l}
1 / 2 \\
1 / 2 \\
1 / 2
\end{array}\right)=\left(\begin{array}{c}
1 / 2 \\
0 \\
0
\end{array}\right) .
\end{aligned}
$$

$(C, c)$ : screw rotation 42 screw rotation axis $\times, 0, \mathrm{l} / 2$

ITA description:

$$
4^{+}(I / 2,0,0) \times, 0, I / 2
$$

## Problem: Geometric Interpretation of (W,w) <br> SYMMETRY OPERATION

## Geometric Interpretation of Matrix Column Representation of Symmetry Operation

## Symmetry Operation

This program calculates the geometric interpretation of matrix column representation of symmetry operation for a given crystal system or space group.

Inpunt:
i) The crystal system or the space group number.
ii) The matrix column representation of symmetry operation.

If you want to work on a non conventional setting click on Non conventional setting, this will show you a form where you have to introduce the transformation matrix relating the conventional setting of the group you have chosen with the non conventional one you are interested in.

Output:
We obtain the symmetry operation.

Please, introduce the crystal system

Or please, enter the sequential number of group as given in the International Tables for Crystallography, Vol. A

Matrix column representation of symmetry operation


Standard/Default Setting
Standard/Default Setting

## Problem I. 3

I. Solve the problems I.I and I. 2 applying the program SYMMETRY OPERATION

## Problem I. 4

I. Characterize geometrically the matrix-column pairs listed under General position of the space group P4mm in ITA. Compare the results with the data listed under Symmetry operations.
2.

Consider the diagram of the symmetry elements of P4mm. Try to determine the matrix-column pairs of the symmetry operations whose symmetry elements are indicated on the unit-cell diagram.

## P4mm

 $C_{4 v}^{1}$P4mm
No. 99

4 mm
Tetragonal


Origin on 4 mm
Asymmetric unit $0 \leq x \leq \frac{1}{2} ; \quad 0 \leq y \leq \frac{1}{2} ; \quad 0 \leq z \leq 1 ; \quad x \leq y$
Symmetry operations
(1) 1
(2) $20,0, z$
(3) $4^{+} 0,0, z$
(4) $4^{-} 0,0, z$
(5) $m x, 0, z$
(6) $m 0, y, z$
(7) $m x, x, z$
(8) $m x, x, z$

Generators selected (1); $t(1,0,0) ; t(0,1,0) ; t(0,0,1) ;(2) ;(3) ;(5)$

## Positions

Multiplicity,
Coordinates
Wyckoff letter,
Site symmetry
$8 \quad g \quad 1$
(1) $x, y, z$
(2) $\bar{x}, \bar{y}, z$
(3) $\bar{y}, x, z$
(4) $y, \bar{x}, z$
(5) $x, \bar{y}, z$
(6) $\bar{x}, y, z$
(7) $\bar{y}, \bar{x}, z$
(8) $y, x, z$

## GENERATION <br> OF <br> SPACE GROUPS

## Generators

Set of generators of a group is a set of spacegroup elements such that each element of the group can be obtained as an ordered product of the generators

$$
\mathrm{W}=\mathrm{G}_{h}^{k_{h}} * \mathrm{G}_{h-1}^{k_{h-1}} * \ldots * \mathrm{G}_{3}^{k_{3}} * \mathrm{G}_{2}^{k_{2}} * \mathrm{G}_{1}
$$

GI - identity
$G_{2}, G_{3}, G_{4}$ - primitive translations
$\mathrm{G}_{5}, \mathrm{G}_{6}$ - centring translations
$G_{7}, G_{8}, \ldots$ - generate the rest of elements

## Generation of trigonal and hexagonal groups

| 3 | 3 |
| :--- | :--- |
| $\overline{3}$ | $3, \overline{1}$ |
| 321 | $3,2_{110}$ |
| (rhombohedral coordinates | $\left.3{ }_{111}, 2_{10 \overline{1}}\right)$ |
| 312 | $3,2_{1 \overline{1} 0}$ |
| $3 m 1$ | $3, m_{110}$ |
| (rhombohedral coordinates | $\left.3_{111}, m_{10 \overline{1}}\right)$ |
| $31 m$ | $3, m_{1 \overline{1} 0}$ |
| $\overline{3} m 1$ | $3,2_{110}, \overline{1}$ |
| (rhombohedral coordinates | $\left.32_{111}, 2_{10 \overline{1}}, \overline{1}\right)$ |
| $\overline{3} 1 \mathrm{~m}$ | $3,2_{1 \overline{1} 0}, \overline{1}$ |
| 6 | $3,2_{z}$ |
| $\overline{6}$ | $3, m_{z}$ |
| $6 / m$ | $3,2_{z}, \overline{1}$ |
| 622 | $3,2_{z}, 2_{110}$ |
| 6 mm | $3,2_{z}, m_{110}$ |
| $\overline{6} \mathrm{~m} 2$ | $3, m_{z}, m_{110}$ |
| $\overline{6} 2 \mathrm{~m}$ | $3, m_{z}, 2_{110}$ |
| $6 / \mathrm{mmm}$ | $3,2_{z}, 2_{110}, \overline{1}$ |



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## Generation of orthorhombic and tetragonal groups

| Hermann-Mauguin symbol of <br> crystal class | Generators $\mathrm{G}_{i}$ (sequence left to <br> right) |
| :--- | :--- |
| 1 | 1 |
| $\overline{1}$ | $\overline{1}$ |
| 2 | 2 |
| $m$ | $m$ |
| $2 / m$ | $2, \overline{1}$ |
| 222 | $2_{z}, 2_{y}$ |
| $m m 2$ | $2_{z}, m_{y}$ |
| $m m m$ | $2_{z}, 2_{y}, \overline{1}$ |
| 4 | $2_{z}, 4$ |
| $\overline{4}$ | $2_{z}, \overline{4}$ |
| $4 / m$ | $2_{z}, 4, \overline{1}$ |
| 422 | $2_{z}, 4,2_{y}$ |
| $4 m m$ | $2_{z}, 4, m_{y}$ |
| $\overline{4} 2 \mathrm{~m}$ | $2_{z}, \overline{4}, 2_{y}$ |
| $\overline{4} m 2$ | $2_{z}, \overline{4}, m_{y}$ |
| $4 / \mathrm{mmm}$ | $2_{z}, 4,2_{y}, \overline{1}$ |



## EXERCISES

## Problem I. 5

Generate the space group P4mm using the selected generators

Compare the results of your calculation with the coordinate triplets listed under General position of the ITA data of P4mm

Compare the results of your calculations with the BCS data using the retrieval tools GENPOS (generators and general positions)

## P4mm

 $C_{4 v}^{1}$P4mm
No. 99

4 mm
Tetragonal


Origin on 4 mm
Asymmetric unit $0 \leq x \leq \frac{1}{2} ; \quad 0 \leq y \leq \frac{1}{2} ; \quad 0 \leq z \leq 1 ; \quad x \leq y$
Symmetry operations
(1) 1
(2) $20,0, z$
(3) $4^{+} 0,0, z$
(4) $4^{-} 0,0, z$
(5) $m x, 0, z$
(6) $m 0, y, z$
(7) $m x, x, z$
(8) $m x, x, z$

Generators selected (1); $t(1,0,0) ; t(0,1,0) ; t(0,0,1) ;(2) ;(3) ;(5)$

## Positions

Multiplicity,
Coordinates
Wyckoff letter,
Site symmetry
$8 \quad g \quad 1$
(1) $x, y, z$
(2) $\bar{x}, \bar{y}, z$
(3) $\bar{y}, x, z$
(4) $y, \bar{x}, z$
(5) $x, \bar{y}, z$
(6) $\bar{x}, y, z$
(7) $\bar{y}, \bar{x}, z$
(8) $y, x, z$

## SITE-SYMMETRY

## GENERAL POSITION SPECIALWYCKOFF POSITIONS

## Calculation of the Site-symmetry groups

$$
\begin{aligned}
& \text { Group P-I } \begin{array}{l}
\text { Positions } \\
\begin{array}{l}
\text { Multiplicity, } \\
\text { Wyckoff leter, } \\
\text { Site symmetry }
\end{array}
\end{array} \\
& \text { Coordinates } \\
& 2 \quad i \quad 1 \\
& \text { (1) } x, y, z \\
& \text { (2) } \bar{x}, \bar{y}, \bar{z} \\
& S=\left\{(W, w),(W, w) X_{o}=X_{o}\right\} \\
& \begin{array}{|c|}
\hline 1 / 2 \\
\hline 0 \\
\hline 1 / 2 \\
\hline-1 / 2 \\
\hline
\end{array} \\
& S_{f}=\left\{(1,0),(-I, 10 I) X_{f}=X_{f}\right\} \\
& S_{f} \simeq\{I,-I\} \\
& \text { isomorphic }
\end{aligned}
$$

## EXERCISES

## Problem I. 6

Consider the special Wyckoff positions of the the space group P4mm.

Determine the site-symmetry groups of Wyckoff positions la and 2 b . Compare the results with the listed ITA data

The coordinate triplets $(x, I / 2, z)$ and $(I / 2, x, z)$, belong to Wyckoff position 4 f . Compare their site-symmetry groups.

## CONTINUED

Space group P4mm

Generators selected (1); $t(1,0,0) ; t(0,1,0) ; t(0,0,1) ;(2) ;(3) ;(5)$

## Positions

Multiplicity,
Wyckoff letter,
Site symmetry
$8 \quad g \quad 1$
(1) $x, y, z$
(2) $\bar{x}, \bar{y}, z$
(3) $\bar{y}, x, z$
(4) $y, \bar{x}, z$
(5) $x, \bar{y}, z$
(6) $\bar{x}, y, z$
(7) $\bar{y}, \bar{x}, z$
(8) $y, x, z$

| 4 | $f$ | .$m$. | $x, \frac{1}{2}, z$ | $\bar{x}, \frac{1}{2}, z$ | $\frac{1}{2}, x, z$ | $\frac{1}{2}, \bar{x}, z$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 4 | $e$ | .$m$. | $x, 0, z$ | $\bar{x}, 0, z$ | $0, x, z$ | $0, \bar{x}, z$ |
| 4 | $d$ | $\ldots m$ | $x, x, z$ | $\bar{x}, \bar{x}, z$ | $\bar{x}, x, z$ | $x, \bar{x}, z$ |
| 2 | $c$ | $2 m m$. | $\frac{1}{2}, 0, z$ | $0, \frac{1}{2}, z$ |  |  |
| 1 | $b$ | $4 m m$ | $\frac{1}{2}, \frac{1}{2}, z$ |  |  |  |

## EXERCISES

## Problem 1.7

Consider the data given in ITA for the space group $P 4_{2} / m b c$, No. 135:
Generate the representatives of the General Position from the generators of the group. Starting from $\mathcal{T}_{\mathcal{G}}$, construct the chain of normal subgroups along which the space group $P 4_{2} / m b c$ is step-wise generated;
Determine the site-symmetry groups of the following Wyckoff positions: $4(a) ; 4(c) ; 4(d) ; 8(g)$. Construct the corresponding oriented site-symmetry symbols and compare them with those listed in ITA;
Characterize geometrically the isometries (3), (8), (12), (15) and (16) as listed under General Position. Compare the results with the corresponding geometric descriptions listed under Symmetry operations in ITA.

International Tables for Crystallography (2006). Vol. A, Space group 135, pp. 466-467.
$P 4_{2} / m b c \quad D_{4 h}^{13}$
$4 / \mathrm{mmm}$
Tetragonal
No. 135
$P 4_{2} / m 2_{1} / b 2 / c$


Origin at centre $(2 / m)$ at $4 / m 1 n$
Asymmetric unit $0 \leq x \leq \frac{1}{2} ; \quad 0 \leq y \leq \frac{1}{2} ; \quad 0 \leq z \leq \frac{1}{4}$

## Symmetry operations

(1) 1
(2) $20,0, z$
(3) $4^{+}\left(0,0, \frac{1}{2}\right) \quad 0,0, z$
(4) $4^{-}\left(0,0, \frac{1}{2}\right) \quad 0,0, z$
(5) $2\left(0, \frac{1}{2}, 0\right) \frac{1}{4}, y, 0$
(6) $2\left(\frac{1}{2}, 0,0\right) x, \frac{1}{4}, 0$
(7) $2\left(\frac{1}{2}, \frac{1}{2}, 0\right) x, x, \frac{1}{4}$
(8) $2 x, \bar{x}+\frac{1}{2}, \frac{1}{4}$
(9) $\overline{1} \quad 0,0,0$
(10) $m x, y, 0$
(11) $\overline{4}+0,0, z ; 0,0, \frac{1}{4}$
(12) $\overline{4}^{-} 0,0, z ; 0,0, \frac{1}{4}$
(13) $a x, \frac{1}{4}, z$
(14) $b \frac{1}{4}, y, z$
(15) $c \quad x+\frac{1}{2}, \bar{x}, z$
(16) $n\left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right) \quad x, x, z$

Generators selected (1); $t(1,0,0) ; t(0,1,0) ; t(0,0,1) ;(2) ;(3) ;(5) ;(9)$

## Positions

Multiplicity,
Wyckoff letter,
Site symmetry
$16 \quad i \quad 1$
(1) $x, y, z$
(4) $y, \bar{x}, z+\frac{1}{2}$
(8) $\bar{y}+\frac{1}{2}, \bar{x}+\frac{1}{2}, \bar{z}+\frac{1}{2}$
(12) $\bar{y}, x, \bar{z}+\frac{1}{2}$
(9) $\bar{x}, \bar{y}, \bar{z}$
(13) $x+\frac{1}{2}, \bar{y}+\frac{1}{2}, z$
(16) $y+\frac{1}{2}, x+\frac{1}{2}, z+\frac{1}{2}$
(2) $\bar{x}, \bar{y}, z$
(3) $\bar{y}, x, z+\frac{1}{2}$
(10) $x, y, \bar{z}$
(7) $y+\frac{1}{2}, x+\frac{1}{2}, \bar{z}+\frac{1}{2}$
(14) $\bar{x}+\frac{1}{2}, y+\frac{1}{2}, z$
(11) $y, \bar{x}, \bar{z}+\frac{1}{2}$

Coordinates
(15) $\bar{y}+\frac{1}{2}, \bar{x}+\frac{1}{2}, z+\frac{1}{2}$

Reflection conditions

General:
$0 k l: k=2 n$
$h h l: l=2 n$
$00 l: l=2 n$
$h 00: h=2 n$
Special: as above, plus
no extra conditions
$h k l: l=2 n$
$h k l: h+k, l=2 n$
$h k l: h+k, l=2 n$
$h k l: h+k, l=2 n$
$h k l: h+k, l=2 n$
$h k l: h+k, l=2 n$
$h k l: h+k, l=2 n$

## CO-ORDINATE TRANSFORMATIONS IN <br> CRYSTALLOGRAPHY

## General affine transformation


a change of basis from $(\mathbf{a}, \mathbf{b})$ to $\left(\mathbf{a}^{\prime}, \mathbf{b}^{\mathbf{\prime}}\right)$
a shift of origin from O to O' by a shift vector $\boldsymbol{p}$ with components $p_{1}$ and $p_{2}$

Change in the coordinates of the point X from ( $\mathrm{x}, \mathrm{y}$ ) to ( $\mathrm{x}^{\prime}, \mathrm{y}^{\prime}$ )

## Problem: BASIS TRANSFORMATION



## 3-dimensional space

$(\mathbf{a}, \mathbf{b}, \mathbf{c})$, origin O : point $\mathrm{X}(x, y, z)$
$(P, p) \downarrow$
$\left(\mathbf{a}^{\prime}, \mathbf{b}^{\prime}, \mathbf{c}^{\prime}\right)$, origin $\mathrm{O}^{\prime}:$ point $\mathrm{X}\left(x^{\prime}, y^{\prime}, z^{\prime}\right)$

Transformation of symmetry operations ( $\mathrm{W}, \mathrm{w}$ ):

$$
\left(W^{\prime}, w^{\prime}\right)=(P, p)^{-1}(W, w)(P, p)
$$

## 3-dimensional space

$(\mathbf{a}, \mathbf{b}, \mathbf{c})$, origin O : point $\mathrm{X}(x, y, z)$ $(\mathbf{P}, \boldsymbol{p}) \downarrow$
$\left(\mathbf{a}^{\prime}, \mathbf{b}^{\prime}, \mathbf{c}^{\prime}\right)$, origin $\mathrm{O}^{\prime}$ : point $\mathrm{X}\left(x^{\prime}, y^{\prime}, z^{\prime}\right)$
(i) linear part: change of orientation or length

$$
\left(\mathbf{a}^{\prime}, \mathbf{b}^{\prime}, \mathbf{c}^{\prime}\right)=(\mathbf{a}, \mathbf{b}, \mathbf{c}) \boldsymbol{P}
$$

$$
=(\mathbf{a}, \mathbf{b}, \mathbf{c})\left(\begin{array}{lll}
P_{11} & P_{12} & P_{13} \\
P_{21} & P_{22} & P_{23} \\
P_{31} & P_{32} & P_{33}
\end{array}\right) \quad \begin{gathered}
\left(P_{11} \mathbf{a}+P_{21} \mathbf{b}+P_{31} \mathbf{c},\right. \\
P_{12} \mathbf{a}+P_{22} \mathbf{b}+P_{32} \mathbf{c}, \\
\left.P_{13} \mathbf{a}+P_{23} \mathbf{b}+P_{33} \mathbf{c}\right) .
\end{gathered}
$$

(ii) origin shift by a shift vector $\mathbf{P}\left(\mathrm{P}_{1}, \mathrm{P}_{2}, \mathrm{P}_{3}\right)$ :

$$
O^{\prime}=O+p
$$

the origin $\boldsymbol{O}^{\prime}$ has
coordinates ( $\mathrm{P}_{1}, \mathrm{P}_{2}, \mathrm{P}_{3}$ ) in the old coordinate system

## Transformation of the coordinates of a point $X(x, y, z)$ :

$$
\begin{array}{rlr}
\left(\begin{array}{l}
x^{\prime} \\
y^{\prime} \\
z^{\prime}
\end{array}\right) & =\boldsymbol{Q}\left(\begin{array}{l}
x \\
y \\
z
\end{array}\right)+\boldsymbol{q} & \text { with } \\
& \begin{array}{l}
\boldsymbol{Q}=\boldsymbol{P}^{-1} \\
\boldsymbol{q}=-\boldsymbol{P}^{-1} \boldsymbol{p} .
\end{array} \\
& =\left(\begin{array}{l}
Q_{11} x+Q_{12} y+Q_{13} z+q_{1} \\
Q_{21} x+Q_{22} y+Q_{23} z+q_{2} \\
Q_{31} x+Q_{32} y+Q_{33} z+q_{3}
\end{array}\right) . &
\end{array}
$$

## special cases

-origin shift:

$$
\boldsymbol{x}^{\prime}=\boldsymbol{x}-\boldsymbol{p}
$$

-change of basis :

$$
\boldsymbol{x}^{\prime}=\boldsymbol{P}^{-1} \boldsymbol{x}
$$

Transformation of symmetry operations (W,w):


Mapping of mappings
$\left(W^{\prime}, w^{\prime}\right)=(P, p)^{-1}(W, w)(P, p)$

## Matrix formalism: $4 \times 4$ matrices

## augmented matrices:

$\mathbb{W}=\left(\begin{array}{lll|l}W_{11} & W_{12} & W_{13} & w_{1} \\ W_{21} & W_{22} & W_{23} & w_{2} \\ W_{31} & W_{32} & W_{33} & w_{3} \\ \hline 0 & 0 & 0 & 1\end{array}\right), \quad \mathbb{x}=\left(\begin{array}{c}x \\ y \\ z \\ \frac{z}{1}\end{array}\right) ; \quad \mathbb{x}^{\prime}=\left(\begin{array}{c}x^{\prime} \\ y^{\prime} \\ z^{\prime} \\ \hline 1\end{array}\right)$

$$
\mathbb{x}^{\prime}=\mathbb{Q} \mathbb{X}=\mathbb{P}^{-1} \mathbb{X}
$$

$$
\mathbb{W}^{\prime}=\mathbb{Q} \mathbb{W} \mathbb{P}=\mathbb{P}^{-1} \mathbb{W} \mathbb{P}
$$

## Problem: SYMMETRY DATA ITA SETTINGS

## 530 ITA settings of orthorhombic and monoclinic groups

4. SYNOPTIC TABLES OF SPACE-GROUP SYMBOLS

MONOCLINIC SYSTEM


## SYMMETRY DATA:ITA SETTINGS

## Monoclinic descriptions

|  | Transf. | abc | cba | abc | baç | abc | $\overline{\mathrm{a}} \mathrm{cb}$ | Monoclinic axis $b$ <br> Monoclinic axis $c$ <br> Monoclinic axis $a$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| HM | C2/c | C12/c1 | A12/a1 | A112/a | B112/b | B2/b11 | $C 2 / c 11$ | Cell type 1 |
|  |  | $A 12 / n 1$ | $C 12 / n 1$ | B112/n | A112/n | $C 2 / n 11$ | $B 2 / n 11$ | Cell type 2 |
|  |  | I12/a1 | $I 12 / c 1$ | I112/b | I112/a | $I 2 / c 11$ | I2/b11 | Cell type 3 |

## Orthorhombic descriptions

| No. | HM | abc | bā | cab | $\overline{\mathbf{c}} \mathbf{b a}$ | bca | ā̄b |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 33 | $P n a 2_{1}$ | $P n a 2_{1}$ | $P b n 2_{1}$ | $P 2_{1} n b$ | $P 2_{1} c n$ | $P c 2_{1} n$ | $P n 2_{1} a$ |

## EXERCISES

## Problem 2.1

Use the retrieval tools GENPOS (generators and general positions), WYCKPOS (Wyckoff positions and HKLCOND (reflection conditions) for accessing the space-group data. Get the data on general and special positions in different settings either by specifying transformation matrices to new bases, or by selecting one of the 530 settings of the monoclinic and orthorhombic groups listed in ITA.

Consider the General position data of the space group Im-3m (No. 229). Using the option Non-conventional setting obtain the matrix-column pairs of the symmetry operations with respect to a primitive basis, applying the transformation $\left(a^{\prime}, b^{\prime}, c^{\prime}\right)=1 / 2(-a+b+c, a-b+c, a+b-c)$

## CRYSTAL-STRUCTURE DESCRIPTIONS

## Inorganic Crystal Structure Database

$\left.\begin{array}{l}\text { CC=45520 } \\ \hline \text { Title } \\ \hline \text { Redetermination of the oxygen parameters in zircon (Zr Si O4). } \\ \hline \text { Authors } \\ \hline \text { Krstanovic, I.R. } \\ \hline \text { Reference } \\ \hline\end{array} \begin{array}{l}\text { Acta Crystallographica (1958) 11, 896-897 } \\ \text { Link XRef SCOPUS SCIRUS Google }\end{array}\right]$

lattice<br>parameters<br>space group

## asymmetric-unit data

## EXERCISES

## Problem 2.2

## Print 2 entries selected.

CC=Collection Code: [AB2X4]=ANX Form: [cF56]=Pearson: [e d a]=Wyckoff Symbol: [Al2MgO4]=Structure Type: ***Click the ANX, Pearson or Wyckoff Symbol to find structures with that symbol***.

| CC=45520 |
| :--- |
| Title |
| Redetermination of the oxygen parameters in zircon (Zr Si O4). |

## EXERCISES

## Problem 2.2

Structure I: Space group 14//amd, No. I4 I origin choice I at $\overline{4} m 2$
$\mathrm{a}=6.60 \AA \quad \mathrm{c}=5.88 \AA$
$Z r$ :(a) $0,0,0 ; 0, \frac{1}{2}, \frac{1}{4} ; \frac{1}{2}, 0, \frac{3}{4} ; \frac{1}{2}, \frac{1}{2}, \frac{1}{2}$;
$S i:(b) 0,0, \frac{1}{2} ; 0, \frac{1}{2}, \frac{3}{4} ; \frac{1}{2}, 0, \frac{1}{4} ; \frac{1}{2}, \frac{1}{2}, 0$;
$O:(h)(0, u, v ; 0, \bar{u}, v ; u, 0, \bar{v} ; \bar{u}, 0, \bar{v}$; $\left.\bar{u}, \frac{1}{2}, v+\frac{1}{4} ; u, \frac{1}{2}, v+\frac{1}{4} ;\right)$ [and t $u=0.20 ; v=0.34$

## Problem 2.2

Structure 2: Space group 14 //amd, No. I4I origin choice 2 at $2 / m$ at $0,-1 / 4,1 / 8$ from $\overline{4} m 2$ $\mathrm{a}=6.6164 \AA \mathrm{c}=6.015 \AA$

## Coordinate

 transformation$$
p=0,-\mathrm{I} / 4, \mathrm{I} / 8
$$

(i) What are the new coordinates of the $Z r$ atoms?
(ii) What are the new coordinates of the $S i$ atoms?
(iii) What are the new coordinates of the $O$ atom at $0, u, v$ ?
(iv) What are the new coordinates of the other $O$ atoms?

## Problem 2.2

Coordinate transformation
primitive basis description

$$
\mathbf{a}^{\prime}=\mathbf{a} ; \mathbf{b}^{\prime}=\mathbf{b} ; \mathbf{c}^{\prime}=\frac{1}{2}(\mathbf{a}+\mathbf{b}+\mathbf{c})
$$

(v) What are the new coordinates of the first $Z r$ atom?
(vi) What are the new coordinates of the first $S i$ atom?
(vii) What are the new coordinates of the $O$ atom originally a
(viii) What are the lattice parameters of the primitive unit cell

## Problem 2.2

## SOLUTION

Origin 2 description $\quad \boldsymbol{x}=\boldsymbol{x}-\boldsymbol{p}$
(i) $Z r:$ (a) $0, \frac{1}{4}, \frac{\overline{1}}{8} \sim \frac{7}{8} ; 0, \frac{3}{4}, \frac{1}{8} ; \frac{1}{2}, \frac{1}{4}, \frac{5}{8} ; \frac{1}{2}, \frac{3}{4}, \frac{3}{8}$;
(ii) $S i$ : (b) $0, \frac{1}{4}, \frac{3}{8} ; 0, \frac{3}{4}, \frac{5}{8} ; \frac{1}{2}, \frac{1}{4}, \frac{1}{8} ; \frac{1}{2}, \frac{3}{4}, \frac{\overline{1}}{8} \sim \frac{7}{8}$;
(iii) $O:(h) 0,0.20+0.25,0.34-0.125=0,0.45,0.215$.
the rest of oxygen atoms
$0,0.05,0.215 \quad 0.20,0.25,0.535 \quad 0.80,0.25,0.535 \quad 0,0.95,0.785$ $0,0.55,0.785 \quad 0.80,0.75,0.465 \quad 0.20,0.75,0.465$, all also with $\left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right)+$.

$$
0,0.0167,0.198
$$

## Problem 2.2

## SOLUTION

primitive basis description

$$
\begin{aligned}
& \boldsymbol{P}=\left(\begin{array}{rrr}
1 & 0 & 1 / 2 \\
0 & 1 & 1 / 2 \\
0 & 0 & 1 / 2
\end{array}\right) \quad \boldsymbol{P}^{-1}=\left(\begin{array}{ccc}
1 & 0 & \overline{1} \\
0 & 1 & \overline{1} \\
0 & 0 & 2
\end{array}\right) \\
& \boldsymbol{x}^{\prime}=\boldsymbol{P}^{-1} \boldsymbol{x}
\end{aligned}
$$

(v) The new coordinates of the first $Z r$ atom are $0-\frac{7}{8}, \frac{1}{4}-\frac{7}{8}, 2 \cdot \frac{7}{8} \sim \frac{1}{8}, \frac{3}{8}, \frac{3}{4}$.
(vi) The new coordinates of the first $S i$ atom are $0-\frac{3}{8}, \frac{1}{4}-\frac{3}{8}, 2 \cdot \frac{3}{8} \sim \frac{5}{8}, \frac{7}{8}, \frac{3}{4}$.
(vii) The new coordinates of the first $O$ atom are $0-0.215,0.45-0.215,2 \cdot 0.215 \sim 0.785,0.235,0.430$.

## Structure Utilities

## Structure Utilities

Transform Unit Cells
Strain Tensor Calculation
Assignment of Wyckoff Positions
Transform structures to lower symmetry Space Group basis.
Alternative Settings for a given Crystal Structure
Equivalent Descriptions for a given Crystal Structure

## Problem: ALTERNATIVE SETTINGS

## ITA-settings for the space group C2/c (No.l5)

Choose the initial and final space groups symbols
in matrices must be read by columns. $\mathbf{P}$ is the transformation from standard to non-
$(\mathrm{a}, \mathrm{b}, \mathrm{c})_{\mathrm{n}}=(\mathrm{a}, \mathrm{b}, \mathrm{c})_{\mathrm{s}} \mathrm{P}$

| Initial | Final | Setting | P | P |
| :---: | :---: | :---: | :---: | :---: |
| r | r | C $12 / c 1$ | a,b,c | a,b,c |
| $r$ | r | A $12 / \mathrm{n} 1$ | -a-c, b,a | c,b,-a-c |
| $r$ | $r$ | 112/a 1 | c,b,-a-c | -a-c,b,a |
| $r$ | $r$ | A 12/a 1 | c,-b,a | c,-b,a |
| $r$ | r | C $12 / n 1$ | a,-b,-a-c | a,-b,a-c |
| $r$ | $r$ | $112 / c 1$ | -a-c,-b,c | -a-c,-b, |
| $r$ | r | A 11 2/a | c,a,b | b,c,a |
| $r$ | r | B112/n | $\mathrm{a}, \mathrm{a}-\mathrm{c}, \mathrm{b}$ | a,c,-a-b |
| $r$ | r | $1112 / b$ | -a-c,c,b | -a-b,c,b |
| $r$ | r | B112/b | a,c,-b | $\mathrm{a}, \mathrm{c}, \mathrm{b}$ |
| $r$ | r | A 11 2/n | -a-c,a,-b | b,-c,-a-b |
| $r$ | $r$ | 1112/a | c,-a-c,-b | -a-b,-c,a |
| $r$ | $r$ | B2/b 11 | b,c,a | c,a,b |

## Problem: STRUCTURE TRANSFORMATION

## Transform Structure

## Transform Structure

TRANSTRU can transform a structure in two ways:

- To a lower symmetry space group. The transformed structure is given in the low symmetry space group basis, taking care of all possible splittings of the Wyckoff positions.
- With an arbitrary matrix. The structure, including the cell parameters and the atoms in the unit cell, is transformed with an arbitrary matrix introduced by the user.


Transform structure to a subgroup basis
Transform structure with an arbitrary matrix

## Problem: UNIT CELL CELLTRAN TRANSFORMATION

## Transform Unit Cell

## Transform Unit Cell

Given the cell parameters (separated with spaces), the centring and a transformation matrix the program calculates:

- The transformed unit cell.
- The primitive unit cell.
- The reduced unit cell.
- The metric tensors for each cell.
- The standard root tensor (transformation from the conventional to a cartesian basis)


## Cell

Parameters:
444909090
Centering
Please, define the transformation matrix that relates the group and the subgroup bases


## EXERCISES

## Problem 2.2 (cont)

Repeat the calculations of Problem 2.2 applying the corresposponding tools of the Bilbao Crystallographic server. Compare the results.

## Problem: STRUCTURE VISUALIZATION <br> VISUALIZE

## Visualize with Jmol

## Visualize structures with Jmol

Visualize structures using Jmol. Jmol is an open-source Java viewer for chemical structures in 3D. http://www.jmol.org/


## Structure visualization

## View Structure (with Jmol applet)



## Structure visualization

## View Structure (with Jmol applet)



# Subperiodic groups: rod and layer groups 

Rod groups: 3dim groups with I dim translations
polymeric molecules nanotubes uniform magnetic field to bulk crystals
bicrystals interfaces domain walls thin films

Layer groups: 3dim groups with 2dim translations

## Databases for subperiodic groups

International Tables for
Crystallography, Volume
E: Subperiodic groups

## generators

general postitions Wyckoff positions

Data on maximal subgroups
(Aroyo \& Wondratschek)
maximal subgroups of index 2,3 and 4
series of isomorphic subgroups

## Retrieval tools

