



# International Union of Crystallography

## Commission on Mathematical and Theoretical Crystallography



**International School on Fundamental Crystallography**

**Sixth MaThCryst school in Latin America**

**Workshop on the Applications of Group Theory in the Study of Phase  
Transitions**

**Bogotá, Colombia, 26 November - 1<sup>st</sup> December 2018**



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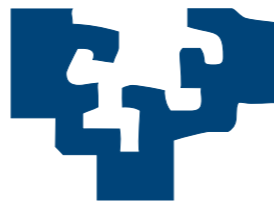


**CPQCOL**  
Consejo Profesional de Química Colombia

# CRYSTALLOGRAPHIC SYMMETRY OPERATIONS

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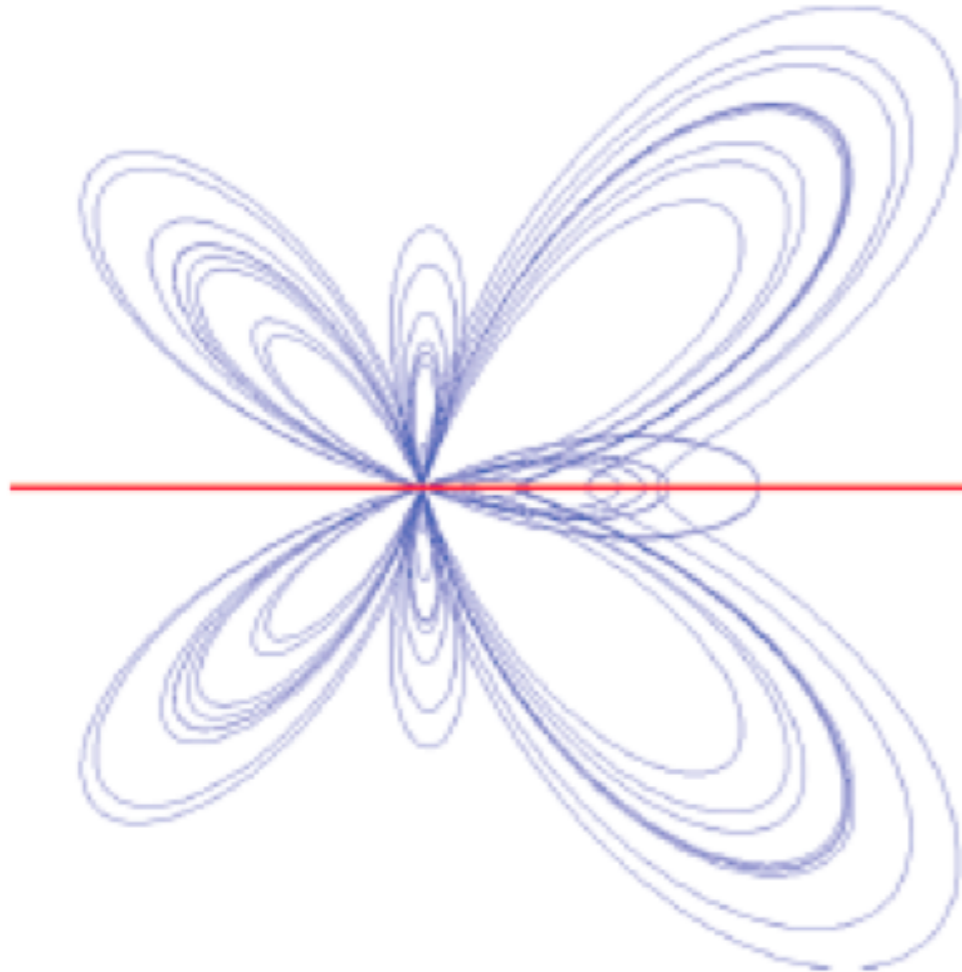
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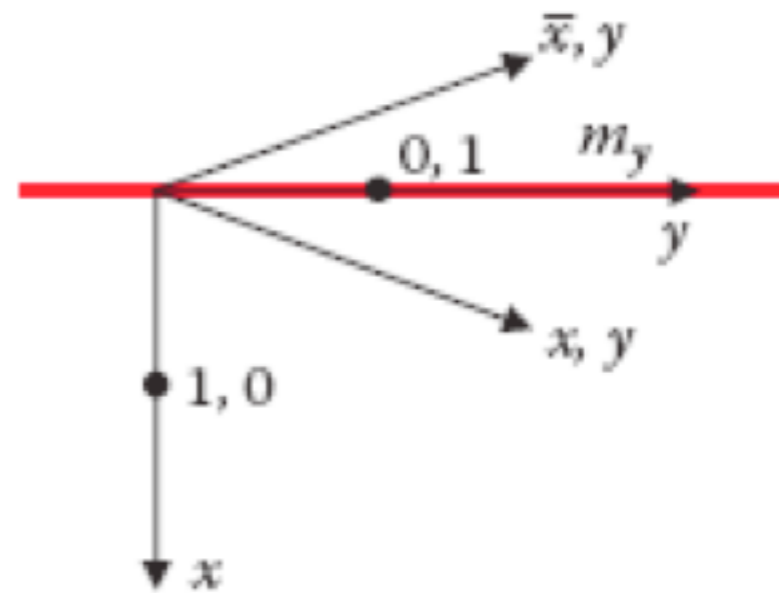
**SYMMETRY OPERATIONS  
AND  
THEIR MATRIX-COLUMN  
PRESENTATION**

# Example: Matrix presentation of symmetry operation

## Mirror symmetry operation



## Mirror line $m_y$ at $0, y$



## Matrix representation

$$m_y \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -x \\ y \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\det \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = ? \quad \text{tr} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = ?$$

## Fixed points

$$m_y \begin{bmatrix} x_f \\ y_f \end{bmatrix} = \begin{bmatrix} x_f \\ y_f \end{bmatrix}$$

drawing: M.M. Julian  
Foundations of Crystallography  
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# Description of isometries

coordinate system:

$\{O, \mathbf{a}, \mathbf{b}, \mathbf{c}\}$

isometry:



$$\tilde{\mathbf{x}} = F_1(\mathbf{x}, \mathbf{y}, \mathbf{z})$$

$$\begin{cases} \tilde{x} & = & W_{11} x + W_{12} y + W_{13} z + w_1 \\ \tilde{y} & = & W_{21} x + W_{22} y + W_{23} z + w_2 \\ \tilde{z} & = & W_{31} x + W_{32} y + W_{33} z + w_3 \end{cases}$$

# Matrix-column presentation of isometries

$$\begin{pmatrix} \tilde{x} \\ \tilde{y} \\ \tilde{z} \end{pmatrix} = \begin{pmatrix} W_{11} & W_{12} & W_{13} \\ W_{21} & W_{22} & W_{23} \\ W_{31} & W_{32} & W_{33} \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}$$

linear/matrix part                      translation column part

$$\tilde{x} = W x + w$$

$$\tilde{x} = (W, w) x \quad \text{or} \quad \tilde{x} = \{ W \mid w \} x$$

matrix-column  
pair

Seitz symbol

# EXERCISES

# Problem 2.14

Referred to an 'orthorhombic' coordinated system ( $a \neq b \neq c$ ;  $\alpha = \beta = \gamma = 90$ ) two symmetry operations are represented by the following matrix-column pairs:

$$(W_1, w_1) = \left( \begin{array}{ccc|c} -1 & & & 0 \\ & 1 & & 0 \\ & & -1 & 0 \end{array} \right)$$

$$(W_2, w_2) = \left( \begin{array}{ccc|c} -1 & & & 1/2 \\ & 1 & & 0 \\ & & -1 & 1/2 \end{array} \right)$$

Determine the images  $X_i$  of a point  $X$  under the symmetry operations  $(W_i, w_i)$  where

$$X = \begin{array}{|c|} \hline 0,70 \\ \hline 0,31 \\ \hline 0,95 \\ \hline \end{array}$$

Can you guess what is the geometric 'nature' of  $(W_1, w_1)$ ?  
And of  $(W_2, w_2)$ ?

*Hint:*

A drawing could be rather helpful

# EXERCISES

# Problem 2.14

Characterization of the symmetry operations:

$$\det \begin{pmatrix} -1 & & \\ & 1 & \\ & & -1 \end{pmatrix} = ?$$

$$\text{tr} \begin{pmatrix} -1 & & \\ & 1 & \\ & & -1 \end{pmatrix} = ?$$

What are the fixed points of  $(W_1, w_1)$  and  $(W_2, w_2)$  ?

$$\begin{pmatrix} -1 & & & 1/2 \\ & 1 & & 0 \\ & & -1 & 1/2 \end{pmatrix} \begin{pmatrix} x_f \\ y_f \\ z_f \end{pmatrix} = \begin{pmatrix} x_f \\ y_f \\ z_f \end{pmatrix}$$



# Short-hand notation for the description of isometries

isometry:

$$X \bullet \xrightarrow{(W,w)} \bullet \tilde{X}$$

$$\begin{cases} \tilde{x} = W_{11}x + W_{12}y + W_{13}z + w_1 \\ \tilde{y} = W_{21}x + W_{22}y + W_{23}z + w_2 \\ \tilde{z} = W_{31}x + W_{32}y + W_{33}z + w_3 \end{cases}$$

notation rules:

- left-hand side: omitted
- coefficients 0, +1, -1
- different rows in one line

examples:

-1			1/2
	1		0
		-1	1/2

 $\longrightarrow \left\{ \begin{array}{l} -x+1/2, y, -z+1/2 \\ \bar{x}+1/2, y, \bar{z}+1/2 \end{array} \right.$

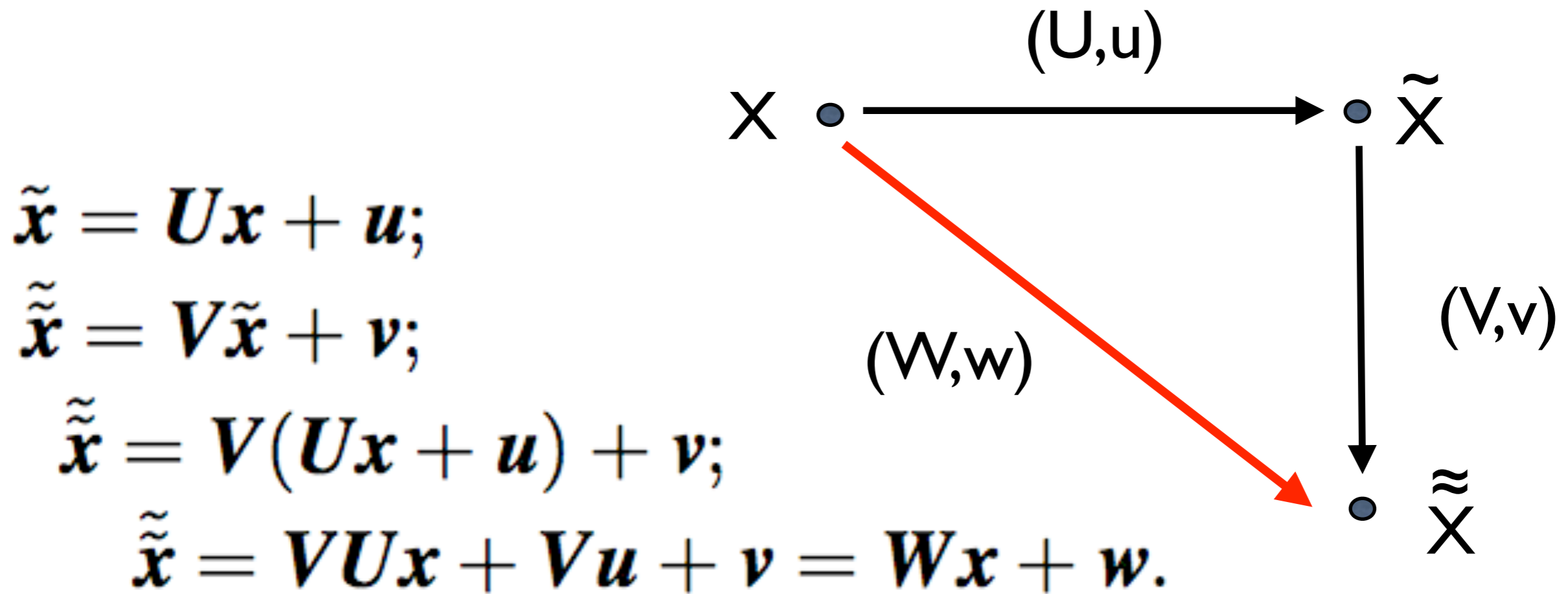
## EXERCISES

### Problem 2.15

Construct the matrix-column pair  $(W, w)$  of the following coordinate triplets:

- (1)  $x, y, z$                       (2)  $-x, y + 1/2, -z + 1/2$   
(3)  $-x, -y, -z$                     (4)  $x, -y + 1/2, z + 1/2$

# Combination of isometries



$$\tilde{\tilde{x}} = (V, v)\tilde{x} = (V, v)(U, u)x = (W, w)x.$$

$$(W, w) = (V, v)(U, u) = (VU, Vu + v).$$

# EXERCISES

## Problem 2.14(cont)

Consider the matrix-column pairs of the two symmetry operations:

$$(W_1, w_1) = \left( \begin{array}{|c|c|c|c|} \hline 0 & -1 & & 0 \\ \hline 1 & 0 & & 0 \\ \hline & & 1 & 0 \\ \hline \end{array} \right) \quad (W_2, w_2) = \left( \begin{array}{|c|c|c|c|} \hline -1 & & & 1/2 \\ \hline & 1 & & 0 \\ \hline & & -1 & 1/2 \\ \hline \end{array} \right)$$

Determine and compare the matrix-column pairs of the combined symmetry operations:

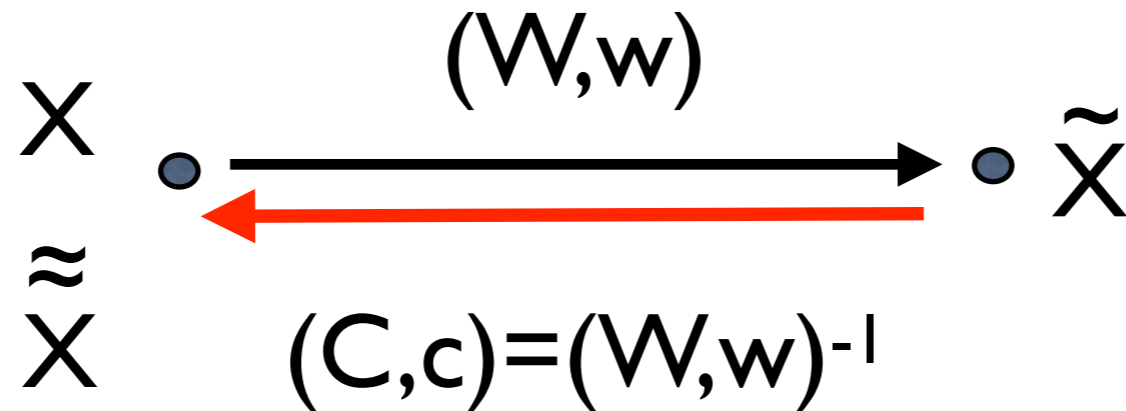
$$(W, w) = (W_1, w_1)(W_2, w_2)$$

$$(W, w)' = (W_2, w_2)(W_1, w_1)$$

combination of isometries:

$$(W_2, w_2)(W_1, w_1) = (W_2 W_1, W_2 w_1 + w_2)$$

# Inverse isometries



$(C, c)(W, w) = (I, \mathbf{o})$

$I = 3 \times 3$  identity matrix  
 $\mathbf{o} =$  zero translation column

$(C, c)(W, w) = (CW, Cw + c)$

$CW = I$

$Cw + c = \mathbf{o}$

$C = W^{-1}$

$c = -Cw = -W^{-1}w$

# EXERCISES

# Problem 2.14(cont)

Determine the inverse symmetry operations  $(W_1, w_1)^{-1}$  and  $(W_2, w_2)^{-1}$  where

$$(W_1, w_1) = \left( \begin{array}{ccc|c} 0 & -1 & & 0 \\ 1 & 0 & & 0 \\ & & 1 & 0 \end{array} \right) \quad (W_2, w_2) = \left( \begin{array}{ccc|c} -1 & & & 1/2 \\ & 1 & & 0 \\ & & -1 & 1/2 \end{array} \right)$$

Determine the inverse symmetry operation  $(W, w)^{-1}$

$$(W, w) = (W_1, w_1)(W_2, w_2)$$

inverse of isometries:

$$(W, w)^{-1} = (W^{-1}, -W^{-1}w)$$

# EXERCISES

## Problem 2.14(cont)

Consider the matrix-column pairs

$$(\mathbf{A}, \mathbf{a}) = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & \bar{1} \end{pmatrix}, \begin{pmatrix} 1/2 \\ 1/2 \\ 1/2 \end{pmatrix} \text{ and } (\mathbf{B}, \mathbf{b}) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

- (i) What is the matrix-column pair resulting from  $(\mathbf{B}, \mathbf{b})(\mathbf{A}, \mathbf{a}) = (\mathbf{C}, \mathbf{c})$ , and  $(\mathbf{A}, \mathbf{a})(\mathbf{B}, \mathbf{b}) = (\mathbf{D}, \mathbf{d})$ ?
- (ii) What is  $(\mathbf{A}, \mathbf{a})^{-1}$ ,  $(\mathbf{B}, \mathbf{b})^{-1}$ ,  $(\mathbf{C}, \mathbf{c})^{-1}$  and  $(\mathbf{D}, \mathbf{d})^{-1}$ ?
- (iii) What is  $(\mathbf{B}, \mathbf{b})^{-1}(\mathbf{A}, \mathbf{a})^{-1}$ ?

# Matrix formalism: 4x4 matrices

augmented  
matrices:

$$\mathbf{x} \longrightarrow \mathbf{X} = \begin{pmatrix} x \\ y \\ z \\ \hline 1 \end{pmatrix}; \quad \tilde{\mathbf{x}} \longrightarrow \tilde{\mathbf{X}} = \begin{pmatrix} \tilde{x} \\ \tilde{y} \\ \tilde{z} \\ \hline 1 \end{pmatrix}$$

$$(\mathbf{W}, \mathbf{w}) \longrightarrow \mathbf{W} = \left( \begin{array}{ccc|c} & & & \\ & \mathbf{W} & & \mathbf{w} \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{array} \right)$$

point  $X \longrightarrow$  point  $\tilde{X}$  :

$$\tilde{\mathbf{X}} = \mathbf{W} \mathbf{X} \quad \begin{pmatrix} \tilde{x} \\ \tilde{y} \\ \tilde{z} \\ \hline 1 \end{pmatrix} = \left( \begin{array}{ccc|c} & & & \\ & \mathbf{W} & & \mathbf{w} \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{array} \right) \begin{pmatrix} x \\ y \\ z \\ \hline 1 \end{pmatrix}$$



## 4x4 matrices: general formulae

point  $X \longrightarrow$  point  $\tilde{X}$  :

$$\tilde{\mathbf{x}} = \mathbf{W} \mathbf{x} \quad \begin{pmatrix} \tilde{x} \\ \tilde{y} \\ \tilde{z} \\ 1 \end{pmatrix} = \left( \begin{array}{ccc|c} & & & \\ & \mathbf{W} & & \mathbf{w} \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{array} \right) \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

combination and inverse of isometries:

$$(\mathbf{W})^{-1} = (\mathbf{W}^{-1}) \quad \mathbf{w}^{-1} = \left( \begin{array}{ccc|c} & & & \\ & \mathbf{W}^{-1} & & -\mathbf{W}^{-1} \mathbf{w} \\ & & & \\ \hline 0 & 0 & 0 & 1 \end{array} \right)$$

$$\mathbf{W}_3 = \mathbf{W}_2 \mathbf{W}_1$$

## EXERCISES

### Problem 2.15 (cont.)

Construct the  $(4 \times 4)$  matrix-presentation of the following coordinate triplets:

$$(1) \ x, y, z \qquad (2) \ -x, y + 1/2, -z + 1/2$$

$$(3) \ -x, -y, -z \qquad (4) \ x, -y + 1/2, z + 1/2$$

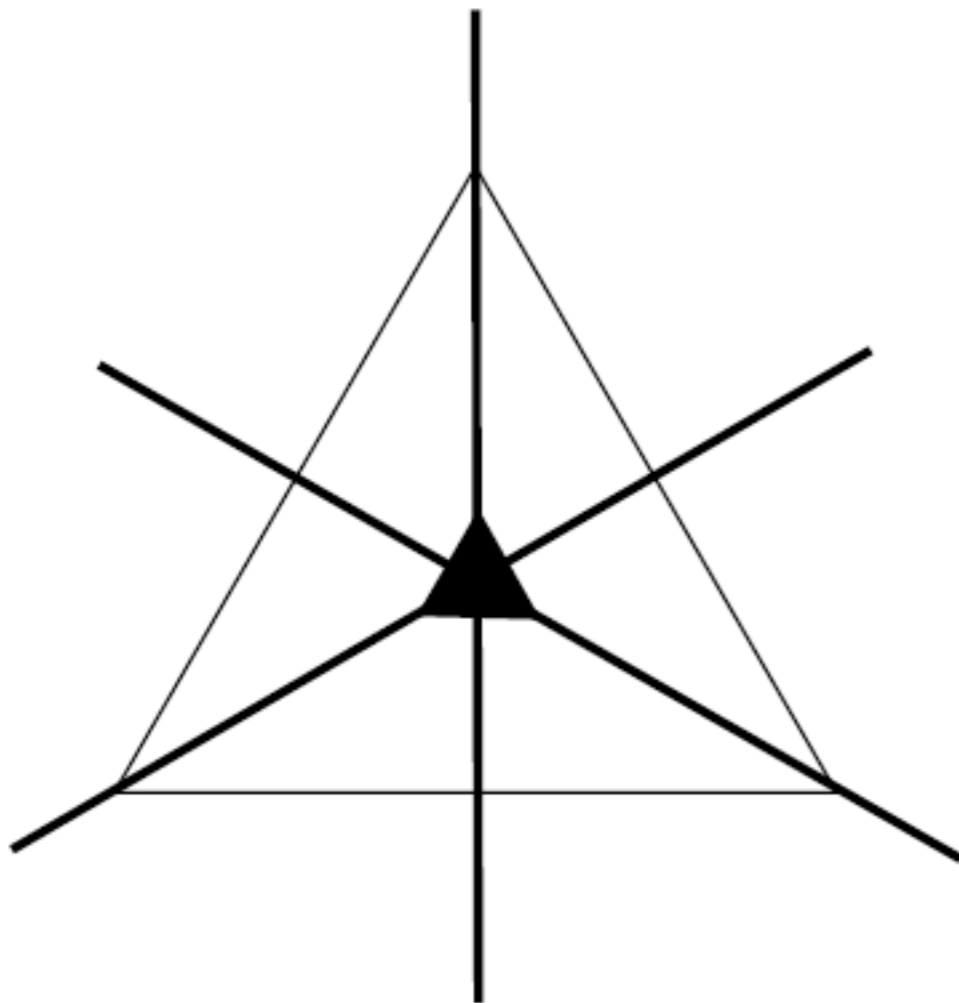
# Crystallographic symmetry operations

## Symmetry operations of an object

The isometries which map the object onto itself are called *symmetry operations of this object*. The *symmetry* of the object is the set of all its symmetry operations.

## Crystallographic symmetry operations

If the object is a crystal pattern, representing a real crystal, its symmetry operations are called *crystallographic symmetry operations*.



The equilateral triangle allows six symmetry operations: rotations by 120 and 240 around its centre, reflections through the three thick lines intersecting the centre, and the identity operation.

# Crystallographic symmetry operations

characteristics:

fixed points of isometries  $(W, w)X_f = X_f$   
geometric elements

Types of isometries preserve handedness

identity:

the whole space fixed

translation  $t$ :

no fixed point

$$\tilde{\mathbf{x}} = \mathbf{x} + \mathbf{t}$$

rotation:

one line fixed  
rotation axis

$$\phi = k \times 360^\circ / N$$

screw rotation:

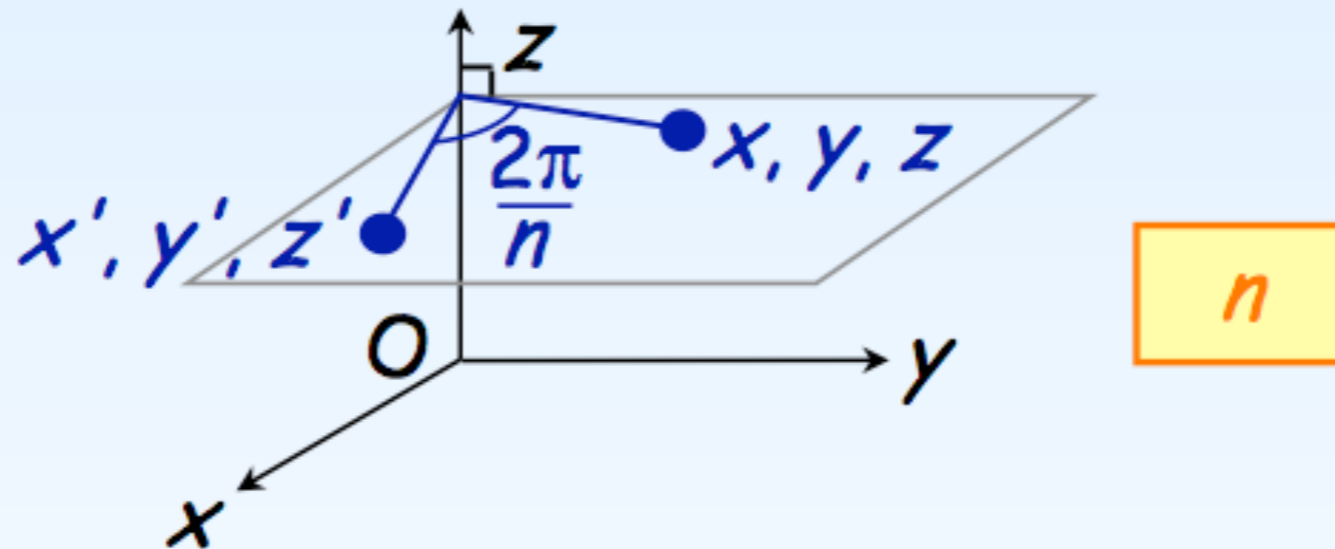
no fixed point  
screw axis

screw vector

# Crystallographic symmetry operations

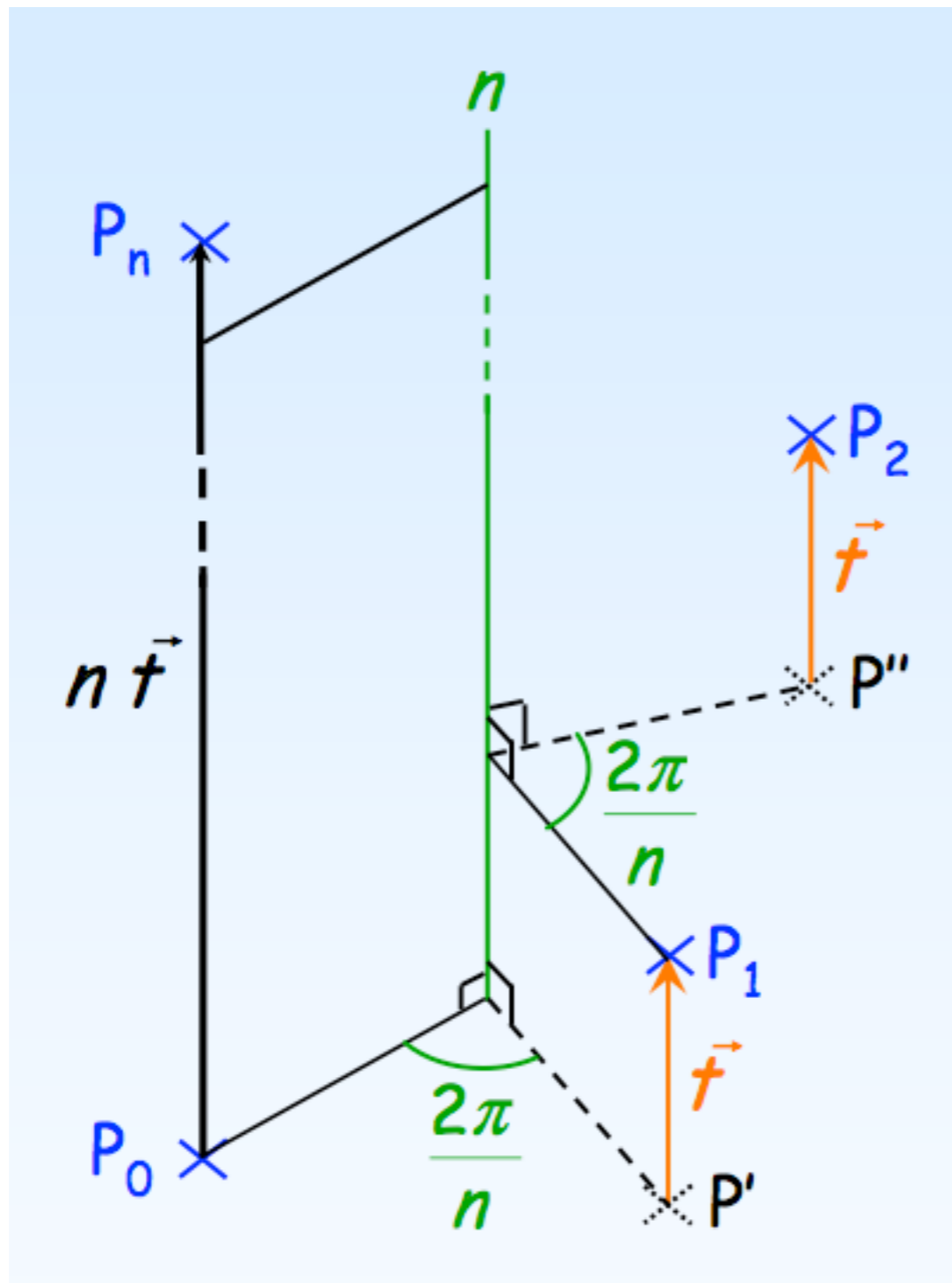
## Rotation (around an axis)

Rotation of order  $n$  = rotation by  $\varphi = \frac{2\pi}{n}$



$$\alpha(n) = \begin{pmatrix} \cos \varphi & -\sin \varphi & 0 \\ \sin \varphi & \cos \varphi & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{Det} = +1$$

## Screw rotation



$n$ -fold rotation followed  
by a fractional  
translation  $\frac{p}{n} \mathbf{t}$  parallel  
to the rotation axis

Its application  $n$  times  
results in a translation  
parallel to the rotation  
axis

## Types of isometries

do not  
preserve handedness

roto-inversion:

centre of roto-inversion fixed  
roto-inversion axis

inversion:

centre of inversion fixed

reflection:

plane fixed  
reflection/mirror plane

glide reflection:

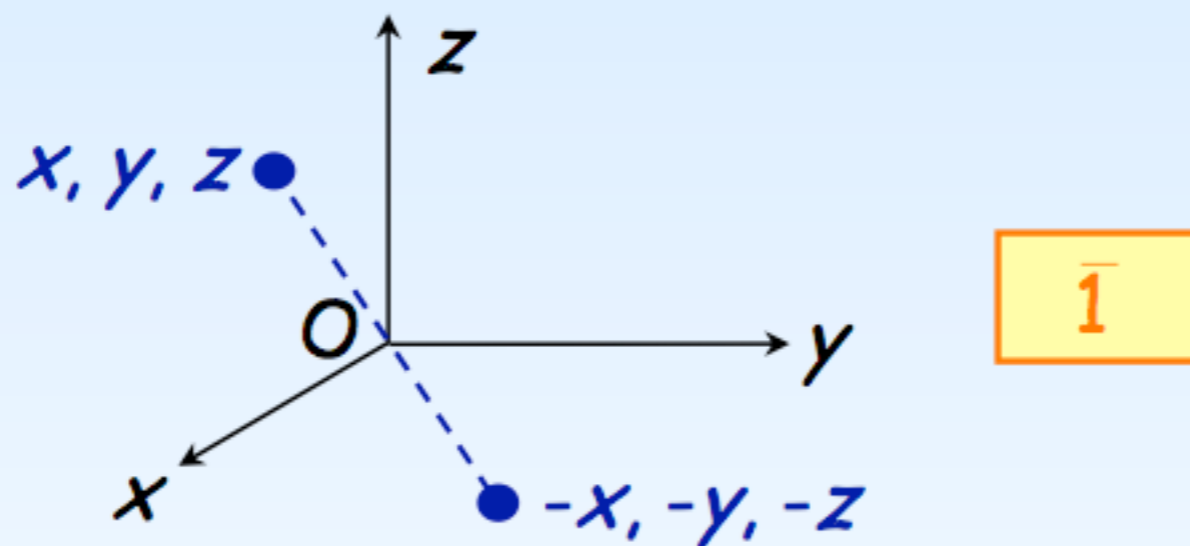
no fixed point  
glide plane

glide vector

# Symmetry operations in 3D

## Rotoinversions

**Inversion** (through a point)



*a crystal which has the inversion symmetry is called **centrosymmetrical**.*

$$\alpha(\bar{1}) = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$\text{Det} = -1$$



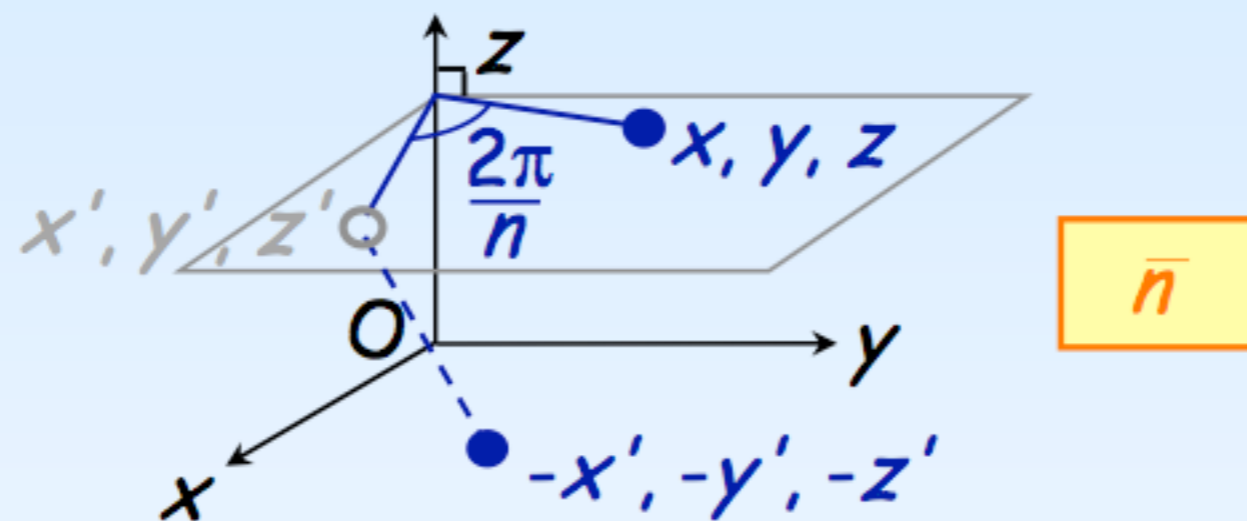
# Symmetry operations in 3D

## Rotoinversions

### Roto-inversion

(around an axis and through a point)

*Rotation followed by an inversion*

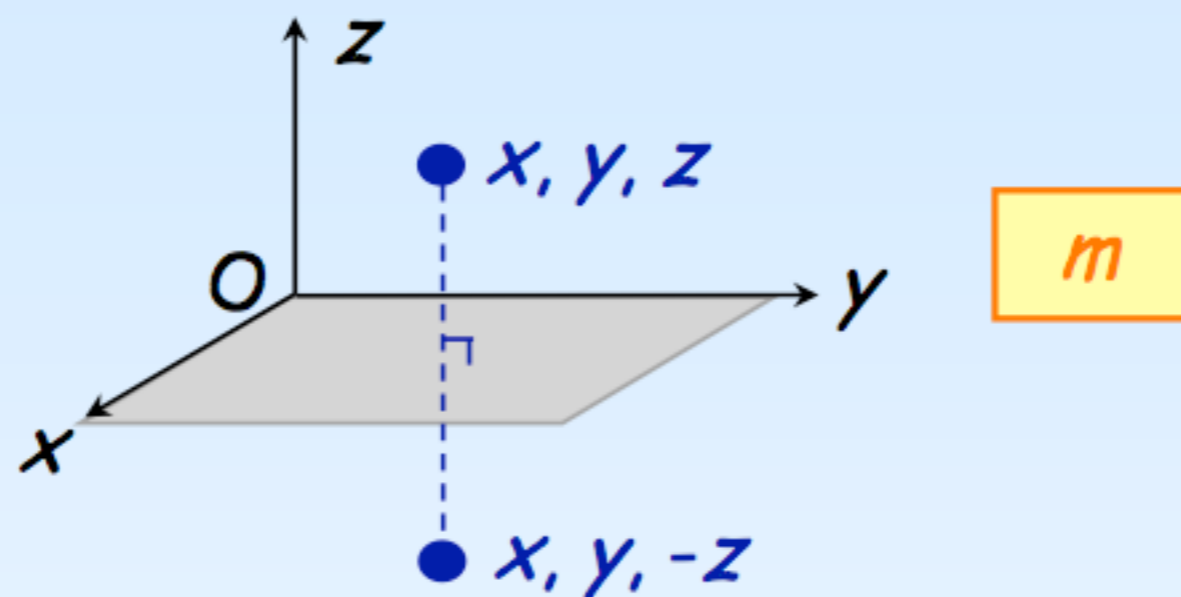


$$\alpha(\bar{n}) = \begin{pmatrix} -\cos\varphi & \sin\varphi & 0 \\ -\sin\varphi & -\cos\varphi & 0 \\ 0 & 0 & -1 \end{pmatrix} \quad \text{Det} = -1$$

# Symmetry operations in 3D

## Rotoinversions

Reflection (through a mirror plane)



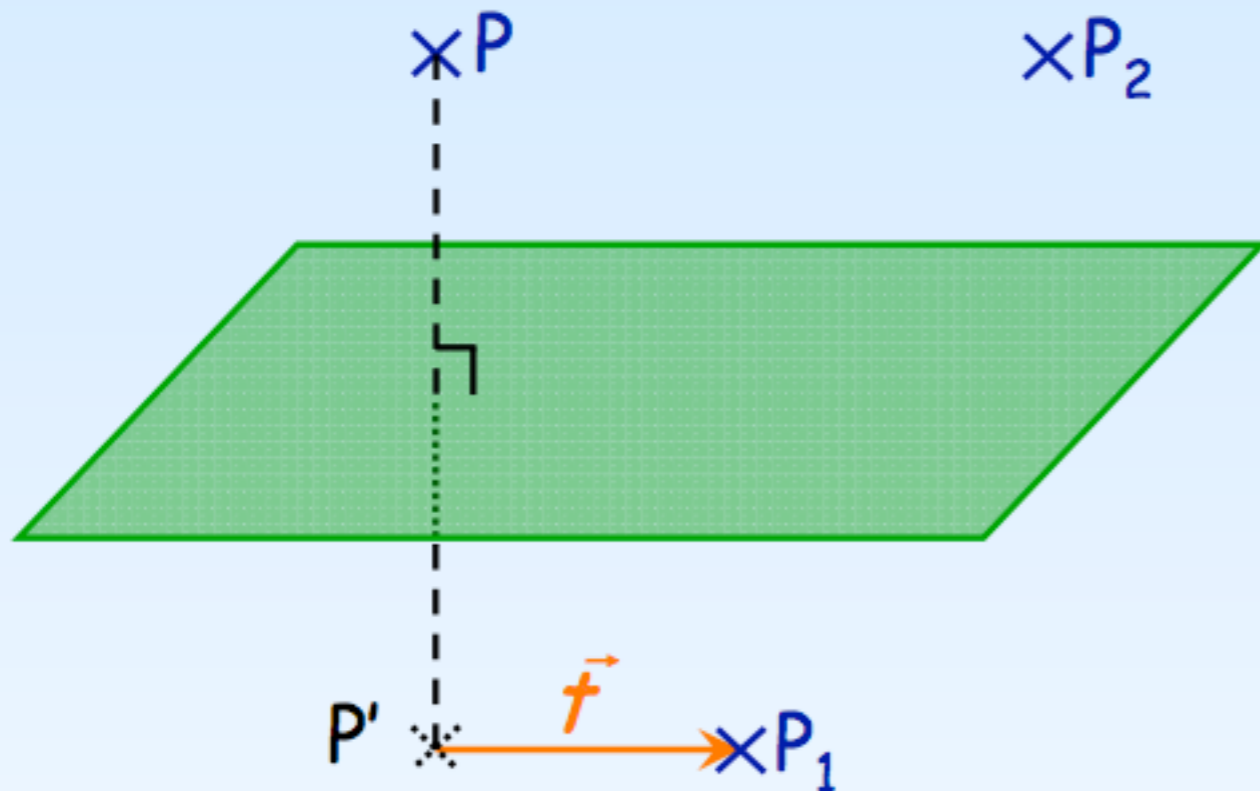
Note that:  $m = \bar{2}$  !

$$\alpha(\bar{1}) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$\text{Det} = -1$$

# Crystallographic symmetry operations

## Glide plane



reflection followed by a fractional translation  $\frac{1}{2}\mathbf{t}$  parallel to the plane

Its application 2 times results in a translation parallel to the plane

# Matrix-column presentation of some symmetry operations

Rotation or roto-inversion around the origin:

$$\begin{pmatrix} W_{11} & W_{12} & W_{13} & 0 \\ W_{21} & W_{22} & W_{23} & 0 \\ W_{31} & W_{32} & W_{33} & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Translation:

$$\begin{pmatrix} 1 & & & w_1 \\ & 1 & & w_2 \\ & & 1 & w_3 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x+w_1 \\ y+w_2 \\ z+w_3 \end{pmatrix}$$

Inversion through the origin:

$$\begin{pmatrix} -1 & & & 0 \\ & -1 & & 0 \\ & & -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -x \\ -y \\ -z \end{pmatrix}$$

**GEOMETRICAL  
INTERPRETATION OF  
MATRIX-COLUMN  
PRESENTATIONS OF  
SYMMETRY OPERATIONS**

# Geometric meaning of $(W, w)$ $W$ information

## (a) type of isometry

	$\det(\mathbf{W}) = +1$					$\det(\mathbf{W}) = -1$				
$\text{tr}(\mathbf{W})$	3	2	1	0	-1	-3	-2	-1	0	1
type	1	6	4	3	2	$\bar{1}$	$\bar{6}$	$\bar{4}$	$\bar{3}$	$\bar{2} = m$
order	1	6	4	3	2	2	6	4	6	2

order:  $\mathbf{W}^n = I$

rotation angle

$$\cos \varphi = (\pm \text{tr}(\mathbf{W}) - 1) / 2$$

Determine the type and order of isometries that are represented by the following matrix-column pairs:

- (1)  $x, y, z$                       (2)  $-x, y+1/2, -z+1/2$   
 (3)  $-x, -y, -z$                     (4)  $x, -y+1/2, z+1/2$

(a) type of isometry

	$\det(\mathbf{W}) = +1$					$\det(\mathbf{W}) = -1$				
$\text{tr}(\mathbf{W})$	3	2	1	0	-1	-3	-2	-1	0	1
type	1	6	4	3	2	$\bar{1}$	$\bar{6}$	$\bar{4}$	$\bar{3}$	$\bar{2} = m$
order	1	6	4	3	2	2	6	4	6	2

# EXERCISES

## Problem 2.14(cont.)

Consider the matrix-column pairs

$$(\mathbf{A}, \mathbf{a}) = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & \bar{1} \end{pmatrix}, \begin{pmatrix} 1/2 \\ 1/2 \\ 1/2 \end{pmatrix} \text{ and } (\mathbf{B}, \mathbf{b}) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

- (i) What is the matrix-column pair resulting from  $(\mathbf{B}, \mathbf{b})(\mathbf{A}, \mathbf{a}) = (\mathbf{C}, \mathbf{c})$ , and  $(\mathbf{A}, \mathbf{a})(\mathbf{B}, \mathbf{b}) = (\mathbf{D}, \mathbf{d})$ ?
- (ii) What is  $(\mathbf{A}, \mathbf{a})^{-1}$ ,  $(\mathbf{B}, \mathbf{b})^{-1}$ ,  $(\mathbf{C}, \mathbf{c})^{-1}$  and  $(\mathbf{D}, \mathbf{d})^{-1}$ ?
- (iii) What is  $(\mathbf{B}, \mathbf{b})^{-1}(\mathbf{A}, \mathbf{a})^{-1}$ ?

Determine the type and order of isometries that are represented by the matrices  $\mathbf{A}$ ,  $\mathbf{B}$ ,  $\mathbf{C}$  and  $\mathbf{D}$ :



Geometric meaning of  $(W, w)$   
 $W$  information

(b) axis or normal direction  $u$ :  $Wu = \pm u$

(b1) rotations:

$$Y(W) = W^{k-1} + W^{k-2} + \dots + W + I$$

(b2) roto-inversions:

$$Y(-W)$$

reflections:

$$Y(-W) = -W + I$$

# Direction of rotation axis/normal

Example:

$$(W, w) = \left( \begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 1/2 \\ 0 & 0 & 1 & 1/2 \end{array} \right)$$

**det W=?**

**tr W=?**

**What is the type and order of the isometry?  
Determine its rotation  
axis?**

$$Y(W) = W^{k-1} + W^{k-2} + \dots + W + I$$

$$Y(W) = \begin{array}{|c|c|c|} \hline 0 & -1 & 0 \\ \hline 1 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline \end{array} + \begin{array}{|c|c|c|} \hline -1 & 0 & 0 \\ \hline 0 & -1 & 0 \\ \hline 0 & 0 & 1 \\ \hline \end{array} + \begin{array}{|c|c|c|} \hline 0 & 1 & 0 \\ \hline -1 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline \end{array} + \begin{array}{|c|c|c|} \hline 1 & 0 & 0 \\ \hline 0 & 1 & 0 \\ \hline 0 & 0 & 1 \\ \hline \end{array} = \begin{array}{|c|c|c|} \hline 0 & 0 & 0 \\ \hline 0 & 0 & 0 \\ \hline 0 & 0 & 4 \\ \hline \end{array}$$

$W^3$                        $W^2$                        $W$                        $I$

Determine the rotation or rotoinversion axes (or normals in case of reflections) of the following symmetry operations

$$(2) -x, y+1/2, -z+1/2$$

$$(4) x, -y+1/2, z+1/2$$

rotations:

$$Y(\mathbf{W}) = \mathbf{W}^{k-1} + \mathbf{W}^{k-2} + \dots + \mathbf{W} + \mathbf{I}$$

reflections:

$$Y(-\mathbf{W}) = -\mathbf{W} + \mathbf{I}$$

# Geometric meaning of $(W, w)$ $W$ information

(c) sense of rotation:

for rotations or  
rotoinversions with  $k > 2$

$$\det(\mathbf{Z}): \mathbf{Z} = [\mathbf{u} | \mathbf{x} | (\det \mathbf{W}) \mathbf{W} \mathbf{x}]$$

$\mathbf{x}$  non-parallel to  $\mathbf{u}$

# Sense of rotation

Example:

$$(W, w) = \left( \begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 1/2 \\ 0 & 0 & 1 & 1/2 \end{array} \right)$$

**det W = 1** **tr W = 1**  
**W = 4001**

**What is its sense of rotation ?**

$$\det(Z): \quad Z = [u | x | (\det W) W x]$$

**det Z = ?**

$$u = \begin{array}{|c|} \hline 0 \\ \hline 0 \\ \hline 1 \\ \hline \end{array}$$

$$x = \begin{array}{|c|} \hline 1 \\ \hline 0 \\ \hline 0 \\ \hline \end{array}$$

$$Wx = \begin{array}{ccc|c} 0 & 1 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array}$$

$$Z = \begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 \end{array}$$

**What is the sense of rotation of the operation**  
 $-y, x-y+1/2, -z+1/2$

# Fixed points of isometries

$$(W, w)X_f = X_f$$

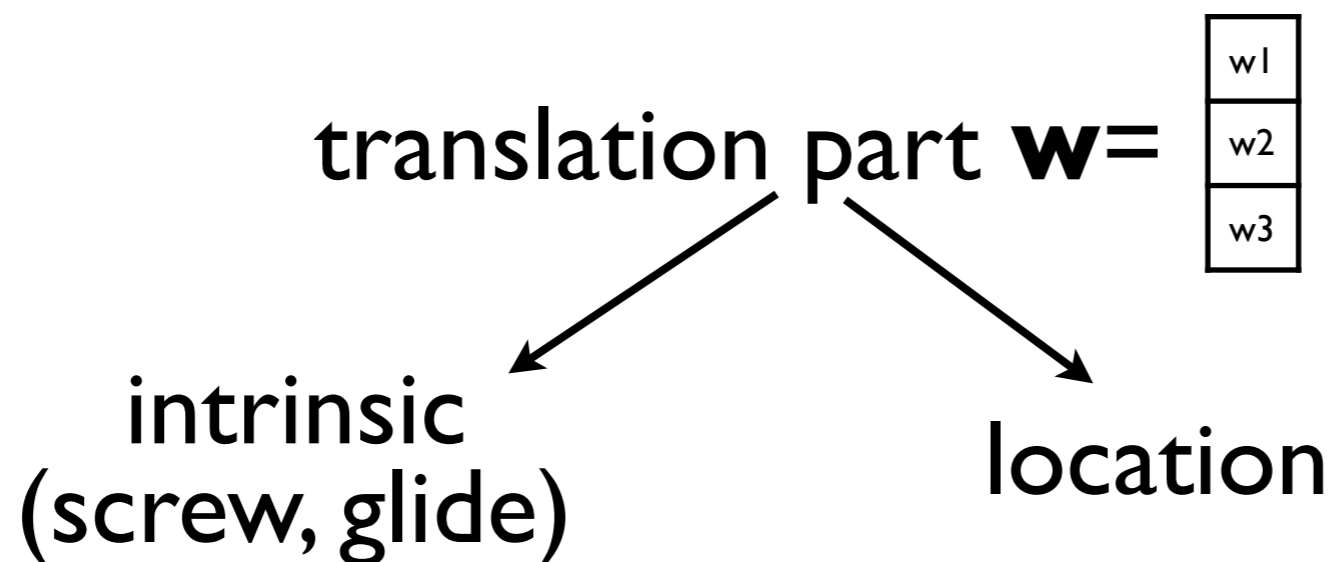
solution:  
point, line, plane or space

**NO solution:**

$$\begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 1/2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1/2 \\ 0 & 0 & -1 & 1/2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

**Fixed points?**



# **Glide** or **Screw** component (intrinsic translation part)

$$(\mathbf{W}, \mathbf{w})^k = (\mathbf{W}, \mathbf{w}) \cdot (\mathbf{W}, \mathbf{w}) \cdot \dots \cdot (\mathbf{W}, \mathbf{w}) = (\mathbf{I}, \mathbf{t})$$

$$(\mathbf{W}, \mathbf{w})^k = (\mathbf{W}^k, (\mathbf{W}^{k-1} + \dots + \mathbf{W} + \mathbf{I})\mathbf{w}) = (\mathbf{I}, \mathbf{t})$$

screw rotations :

$$\mathbf{t}/k = \mathbf{I}/k (\mathbf{W}^{k-1} + \dots + \mathbf{W} + \mathbf{I})\mathbf{w}$$

glide reflections:

$$\mathbf{t}/k = \frac{1}{2} (\mathbf{W} + \mathbf{I})\mathbf{w}$$

Determine the intrinsic translation parts (if relevant) of the following symmetry operations

- |                  |                         |
|------------------|-------------------------|
| (1) $x, y, z$    | (2) $-x, y+1/2, -z+1/2$ |
| (3) $-x, -y, -z$ | (4) $x, -y+1/2, z+1/2$  |

screw rotations:  $\mathbf{t}/k = 1/k (\mathbf{W}^{k-1} + \dots + \mathbf{W} + \mathbf{I})\mathbf{w}$

glide reflections:  $\mathbf{t}/k = \frac{1}{2}(\mathbf{W} + \mathbf{I})\mathbf{w}$



## Fixed points of $(W, w)$

Location (fixed points  $x_F$ ):

(B1)  $t/k = 0$ :

$$(W, w)x_F = x_F$$

(B2)  $t/k \neq 0$ :

$$(W, w_{lp})x_F = x_F$$
$$w_{lp} = w - t/k$$

Determine the fixed points of the following symmetry operations:

- (1)  $x, y, z$                       (2)  $-x, y+1/2, -z+1/2$   
(3)  $-x, -y, -z$                     (4)  $x, -y+1/2, z+1/2$

fixed points:

$$(\mathbf{W}, \mathbf{w}_{lp}) \mathbf{x}_F = \mathbf{x}_F$$

$P2_1/c$

$C_{2h}^5$

$2/m$

$\bar{1}$

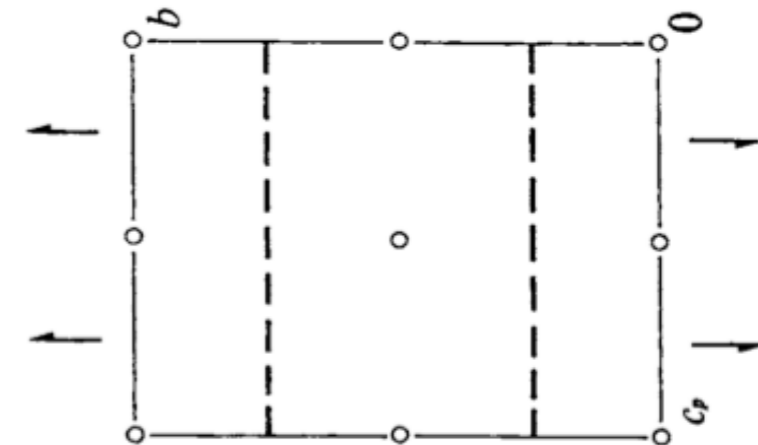
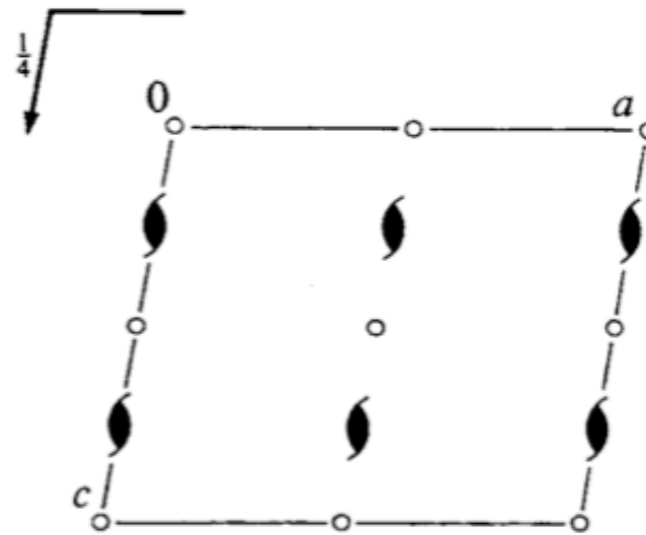
No. 14

$P12_1/c1$

Patterson sy.

UNIQUE AXIS  $b$ , CELL CHOICE 1

EXAMPLE



**Generators selected** (1);  $t(1,0,0)$ ;  $t(0,1,0)$ ;  $t(0,0,1)$ ; (2); (3)

**Positions**

Multiplicity,  
Wyckoff letter,  
Site symmetry

Coordinates

4  $e$  1 (1)  $x, y, z$  (2)  $\bar{x}, y + \frac{1}{2}, \bar{z} + \frac{1}{2}$  (3)  $\bar{x}, \bar{y}, \bar{z}$  (4)  $x, \bar{y} + \frac{1}{2}, z + \frac{1}{2}$

**Symmetry operations**

(1) 1 (2)  $2(0, \frac{1}{2}, 0)$   $0, y, \frac{1}{4}$  (3)  $\bar{1}$   $0, 0, 0$  (4)  $c$   $x, \frac{1}{4}, z$

Matrix-column presentation

Geometric interpretation



FCT/ZTF



### ECM31-Oviedo Satellite

Crystallography online: workshop on the use and applications of the structural tools of the Bilbao Crystallographic Server

20-21 August 2018

NEWS:

- **New Article in Nature**  
07/2017: Bradlyn *et al.* "Topological quantum chemistry" *Nature* (2017). **547**, 298-305.
- **New program: BANDREP**  
04/2017: Band representations and Elementary Band representations of Double Space Groups.
- **New section: Double point and space groups**
  - **New program: DGENPOS**  
04/2017: General positions of Double Space Groups
  - **New program: REPRESENTATIONS DPG**  
04/2017: Irreducible representations of

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Representations and Applications

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Subperiodic Groups: Layer, Rod and Frieze Groups

Structure Databases

Raman and Hyper-Raman scattering

Point-group symmetry

Plane-group symmetry

[www.cryst.ehu.es](http://www.cryst.ehu.es)

**Crystallographic databases**

```
graph TD; A[Crystallographic databases] --> B[Group-subgroup relations]; A --> C[Structural utilities]; A --> D[Representations of point and space groups]; B --> E[Solid-state applications]; C --> E; D --> E;
```

**Group-subgroup relations**

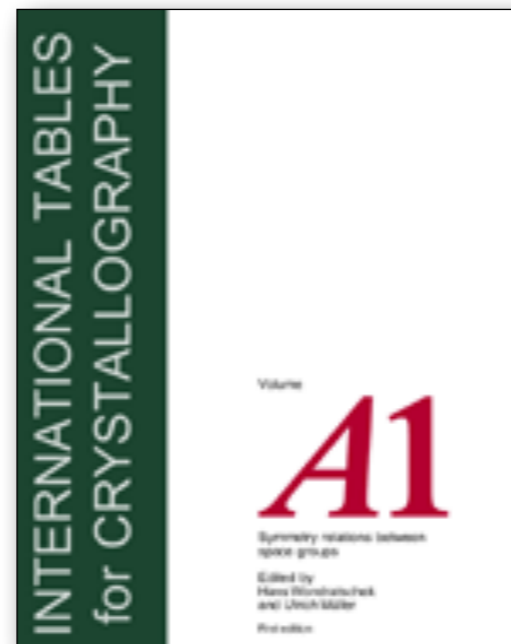
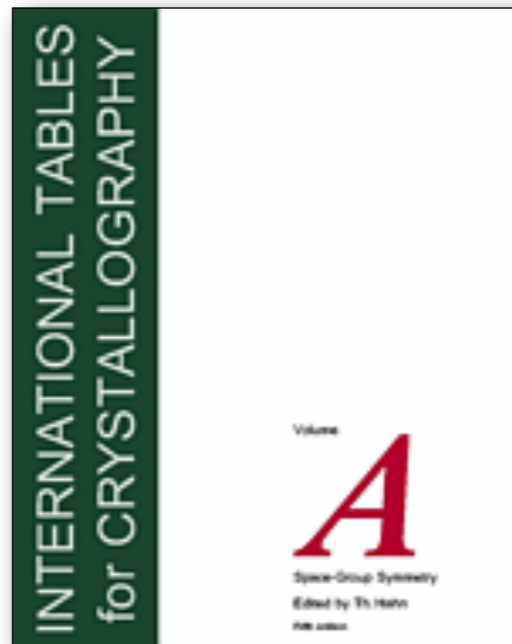
**Structural utilities**

**Representations of point and space groups**

**Solid-state applications**

# Crystallographic Databases

## International Tables for Crystallography



Construct the matrix-column pairs  $(W, w)$  of the following coordinate triplets:

$$(1) \ x, y, z \qquad (2) \ -x, y + 1/2, -z + 1/2$$

$$(3) \ -x, -y, -z \qquad (4) \ x, -y + 1/2, z + 1/2$$

Characterize geometrically these matrix-column pairs taking into account that they refer to a monoclinic basis with unique axis  $b$ ,

Use the program SYMMETRY OPERATIONS for the geometric interpretation of the matrix-column pairs of the symmetry operations.



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04/2017: Irreducible representations of

## Space-group symmetry

<b>GENPOS</b>	Generators and General Positions of Space Groups
<b>WYCKPOS</b>	Wyckoff Positions of Space Groups
<b>HKLCD</b>	Reflection conditions of Space Groups
<b>MAXSUB</b>	Maximal Subgroups of Space Groups
<b>SERIES</b>	Series of Maximal Isomorphic Subgroups of Space Groups
<b>WYCKSETS</b>	Equivalent Sets of Wyckoff Positions
<b>NORMALIZER</b>	Normalizers of Space Groups
<b>KVEC</b>	The k-vector types and Brillouin zones of Space Groups
<b>SYMMETRY OPERATIONS</b>	Geometric interpretation of matrix column representations of symmetry operations
<b>IDENTIFY GROUP</b>	Identification of a Space Group from a set of generators in an arbitrary setting

## Structure Utilities

## Subperiodic Groups: Layer, Rod and Frieze Groups

## Structure Databases

## Raman and Hyper-Raman scattering

## Point-group symmetry

## Plane-group symmetry



## Problem: Geometric Interpretation of (W,w)

## SYMMETRY OPERATION

### Symmetry Operation

This program calculates the geometric interpretation of matrix column representation of symmetry operation for a given crystal system or space group.

Input:

- i) The crystal system or the space group number.
- ii) The matrix column representation of symmetry operation.

If you want to work on a non conventional setting click on **Non conventional setting**, this will show you a form where you have to introduce the transformation matrix relating the conventional setting of the group you have chosen with the non conventional one you are interested in.

Output:

We obtain the geometric interpretation of the symmetry operation.

Introduce the crystal system

monoclinic

Or enter the sequential number of group as given in the *International Tables for Crystallography, Vol. A*

choose it

Matrix column representation of symmetry operation

$-x, y+1/2, -z+1/2$

In matrix form

Rotational part

1	0	0
0	1	0
0	0	1

Translation

0
0
0

Standard/Default Setting

Non Conventional Setting

ITA Settings

$-x, y+1/2, -z+1/2$

$$\begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1/2 \\ 0 & 0 & -1 & 1/2 \end{pmatrix}$$

2 (0, 1/2, 0) 0, y, 1/4

